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# A Compositional Framework for Developing Parallel Programs on Two-Dimensional Arrays

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## Abstract

Computations on two-dimensional arrays such as matrix computations are one of the most fundamental and ubiquitous in computational science and its vast application areas, but development of efficient parallel programs on two-dimensional arrays is known to be hard. In this paper, we propose a compositional framework which supports users, even with little knowledge about parallel machines, to systematically develop both correct and efficient parallel programs on two-dimensional arrays. The key feature of our framework is a novel use of the abide-tree representation of two-dimensional arrays, which not only inherits the advantages of tree representations of matrix where recursive blocked algorithms can be defined to achieve better performance, but also supports transformational development of parallel programs and architecture independent implementation owing to its solid theoretical foundation - the theory of constructive algorithmics.

## 1. INTRODUCTION

Computations on two-dimensional arrays, such as matrix computations, image processing, and relational database managements, are both fundamental and ubiquitous in computational science and its vast application areas [11, 26, 17]. And developing efficient parallel algorithms for these computations is one of the most important topics in many textbooks on parallel programming [16, 28]. Many algorithms have been designed and implemented as standard libraries. For example, for matrix computations [14, 32], we have the useful libraries like ScaLAPACK[10], PLAPACK [1] and RECSY [23]. Though being useful, there are some limitations when using these libraries to develop parallel programs for manipulating two-dimensional arrays.

- First, the libraries are of low abstraction, and thus difficult to be modified or adapted to solve slightly different problems. In fact, the increasing popularity of parallel machines like PC clusters enables more and more users to utilize such parallel computer environments to perform parallel computations of various kinds, which can naturally be slightly different from those libraries provide. The libraries are no direct help for the users in this case, and they have to rewrite or develop the libraries for themselves to serve their purpose. However, since (re-)building parallel libraries is not an easy task, much more involved than sequential algorithm due to necessity of taking the synchronization and communication between processors into consideration, not everyone can do it easily.
- Second, the libraries are not well structured, and thus hard to be efficiently composed together. Often each library is carefully designed with suitable data structures and algorithms so that it can be efficiently executed on specific parallel architectures. This may,

however, prevents us from making efficient use of two libraries developed for two different parallel architectures.

This situation demands a new programming model allowing users to describe parallel computation over two-dimensional arrays in an easy, efficient, but compositional way. As one promising solution to the demand, *skeletal parallel programming* using the parallel skeleton is known [7, 27, 9]. In this model, users can build parallel programs by composing ready-made components (called *skeletons*) that are implemented efficiently in parallel for various parallel architectures. This compositional approach has two major advantages: (1) since low-level parallelism is concealed in skeletons, users can obtain a comparatively efficient parallel program without needing detailed techniques of parallel computers and being unconscious of parallelism explicitly, (2) since the skeletons are designed for structured programming, they can be efficiently composed to solve various problems.

There is much research devoted to parallel skeletons on lists, which is a one-dimensional data structure, and it has been shown [21, 19] that parallel programming with list skeletons is very powerful since we can describe many problems in terms of a few skeletons. Moreover many researches have been done on methods of deriving and optimizing parallel programs by means of parallel skeletons on lists [15, 6, 18], and especially about optimization, and there is a library which can automatically optimize a program described by skeletons [24]. Similarly, for parallel skeletons on the tree data structure there is research on binary trees [31, 13], general trees and derivation of programs on these tree skeletons. Unfortunately, it has proved to be a challenge [25] to design a skeletal framework for developing parallel programs for manipulating two-dimensional arrays.

Generally, a skeleton (compositional) framework for manipulating two-dimensional arrays should consist of the following three parts:

- *a fixed set of parallel skeletons* for manipulating two-dimensional arrays, which cannot only capture fundamental computations on two-dimensional arrays but also be efficiently implemented in parallel for various parallel architectures;
- *a systematic programming methodology*, which can support developing both efficient and correct parallel programs composed by these skeletons; and
- *an automatic optimization mechanism*, which can eliminate inefficiency due to compositional or nested uses of parallel skeletons in parallel programs.

Our idea is to make use of the theory of constructive algorithmics (also known as *Bird-Meertens Formalism*) [4, 30, 2], a successful theory for compositional sequential program development, where aggregate data types are formalized *constructively* as an algebra, and computations on the aggregate data are structured as *recursive* mappings between algebras while enjoying nice algebraic properties for composition with each other.

The key is to formalize two-dimensional arrays constructively so that we can describe computations on them as recursions with maximum (potential) parallelism, allowing implementation to have the maximum freedom to reorder operations for efficiency on parallel architectures. The traditional representations of two-dimensional arrays by nested one-dimensional arrays (row-major or column-major representations) [30, 22] impose much restriction on the access order of elements. Wise et al. represent a two-dimensional array by a quadtree [33] and show that recursive algorithms on quadtree provide better performance than existing algorithms for some matrix computations (QR factorization [12], LU factorization [34]). More examples can be found in [11]. However, the unique representation of two-dimensional arrays by quadtrees does not capture the whole information a two-dimensional data may have. In contrast, Bird [4] represents two-dimensional arrays by dynamic trees allowing restructuring trees when necessary.

In this paper, we propose a compositional framework which allows users, even with little knowledge about parallel machines, to easily describe safe and efficient parallel computation

over two-dimensional arrays, and enables discussion of methods of derivation and optimization of programs. The main contributions of this paper are summarized as follows.

- We propose a *novel use of the abide-tree representation of two-dimensional arrays* [4] in developing *parallel* programs for manipulating two-dimensional arrays, whose importance has not been well recognized in parallel programming community. Our abide-tree representation of two-dimensional arrays not only inherits the advantages of tree representations of matrices where recursive blocked algorithms can be defined to achieve better performance [11, 12, 34], but also supports systematic development of parallel programs and architecture independent implementation owing to its solid theoretical foundation - the theory of constructive algorithmics [4, 2, 30].
- We provide a *strong programming support* for developing both efficient and correct parallel programs on two-dimensional arrays in a highly abstract way (without the need to be concerned with low level implementation). In our framework (Section 4), programmers can easily build up a complicated parallel system by defining basic components *recursively*, combining components *compositionally*, and improving efficiency *systematically*. The power of our approach can be seen from the nontrivial programming examples of matrix multiplication and QR decomposition [12], and a successful derivation of an involved efficient parallel program for the maximum rectangle sum problem [18].
- We demonstrate an *efficient implementation* of basic computation skeletons (in C++ and MPI) on distributed PC clusters, guaranteeing that programs composed by these parallel skeletons can be efficiently executed. So far most research focuses on showing that the recursive tree representation of matrices is suitable for parallel computation on shared memory systems [12, 11], this work shows that the recursive tree representation is also suitable for distributed memory systems. In fact, our parallel skeletons, being of high abstraction with all potential parallelism, are architecture independent.

Our framework can be considered as an extension of the quadtree framework of Wise et al. in the sense that our framework imposes no restriction on the size and the element order of two-dimensional arrays and provides an additional support of derivation and optimization of programs on two-dimensional arrays.

The rest of this paper is organized as follows. In Section 2, we construct a theory of abide tree. In Section 3, we give some examples of parallel algorithms on the abide tree. In Section 4, we demonstrate development of parallel programs on two-dimensional arrays. In Section 5, we give efficient implementations and show their experiments. In Section 6, we remark on the related work and finally in Section 7, we make conclusion.

## 2. THEORY OF TWO-DIMENSIONAL ARRAYS

Before explaining our compositional programming framework, we shall construct a theory of two-dimensional arrays, the basis of our framework, according to the theory of constructive algorithmics [4, 30, 2].

Notation in this paper follows that of Haskell [5], a pure functional language that is able to describe both algorithms and algorithmic transformation concisely. Function application is denoted by a space and the argument may be written without brackets. Thus  $f a$  means  $f(a)$  in ordinary notation. Functions are curried, i.e. functions take one argument and return a function or a value, and the function application associates to the left. Thus  $f a b$  means  $(f a) b$ . The function application binds stronger than any other operator, so  $f a \otimes b$  means  $(f a) \otimes b$ , but not  $f (a \otimes b)$ . Function composition is denoted by  $\circ$ , so  $(f \circ g) x = f (g x)$  from its definition. Binary operators can be used as functions by sectioning as follows:  $a \oplus b = (a \oplus) b = (\oplus) a = (\oplus) a b$ . For arbitrary binary operator  $\otimes$ , an operator in which the arguments are swapped is denoted by  $\tilde{\otimes}$ . Thus  $a \tilde{\otimes} b = b \otimes a$ . Two binary operators  $\ll$  and  $\gg$  are defined by  $a \ll b = a$ ,

$a \gg b = b$ . Pairs are Cartesian products of plural data, written like  $(x, y)$ . A function which applies functions  $f$  and  $g$  respectively to the elements of a pair  $(x, y)$  is denoted by  $(f \times g)$ . Thus  $(f \times g)(x, y) = (f x, g y)$ . A function which applies functions  $f$  and  $g$  separately to an element and returns a pair of the results is denoted by  $(f \Delta g)$ . Thus  $(f \Delta g) a = (f a, g a)$ . A projection function  $\pi_1$  extracts the first element of a pair. Thus  $\pi_1(x, y) = x$ . These can be extended to the case of arbitrary number of elements.

Note that we use functional style notations only for parallel algorithm development; in fact we use the ordinary programming language C++ for practical coding.

## 2.1 Two-Dimensional Arrays in Abide Trees

To represent two-dimensional arrays without loss of information, we define the following abide trees, which are built up by three constructors  $|\cdot|$  (singleton),  $\ominus$  (above) and  $\oplus$  (beside) [4].

$$\begin{aligned} \mathbf{data} \text{ AbideTree } \alpha &= |\cdot| \alpha \\ &| (\text{AbideTree } \alpha) \ominus (\text{AbideTree } \alpha) \\ &| (\text{AbideTree } \alpha) \oplus (\text{AbideTree } \alpha) \end{aligned}$$

Here,  $|\cdot| a$ , or abbreviated as  $|a|$ , means a singleton array of  $a$ , i.e. a two-dimensional array with a single element  $a$ . We define function `the` to extract the element from a singleton array, i.e. `the |a| = a`. For two-dimensional arrays  $x$  and  $y$  which have the same width,  $x \ominus y$  means that  $x$  is located above  $y$ . Similarly, for two-dimensional arrays  $x$  and  $y$  which have the same height,  $x \oplus y$  means that  $x$  is located on the left of  $y$ . Moreover,  $\ominus$  and  $\oplus$  are associative binary operators and satisfy following *abide* (a coined term from above and beside) property.

$$(x \oplus u) \ominus (y \oplus v) = (x \ominus y) \oplus (u \ominus v)$$

In the rest of the paper, we will assume no inconsistency in height or width when  $\oplus$  and  $\ominus$  are used.

Note that one two-dimensional array may be represented by more than one abide trees, but these abide trees are equivalent because of the abide property of  $\ominus$  and  $\oplus$ . For example, we can express the  $2 \times 2$  two-dimensional array

$$\begin{pmatrix} 1 & 2 \\ 3 & 4 \end{pmatrix}$$

by the following two equivalent abide trees.

$$\begin{aligned} &(|1| \oplus |2|) \ominus (|3| \oplus |4|) \\ &(|1| \ominus |3|) \oplus (|2| \ominus |4|) \end{aligned}$$

This is in sharp contrast to the quadtree representation of matrix [12], which does not allow such freedom.

## 2.2 Abide Tree Homomorphism

It follows from the theory of constructive algorithmics [2] that each constructively built-up data structure (i.e., algebraic data structure) is equipped with a powerful computation pattern called homomorphism.

### Definition 2.1 ((Abide Tree) Homomorphism)

A function  $h$  is said to be abide tree homomorphism, if it is defined as follows for a function  $f$  and some binary operators  $\oplus, \otimes$ .

$$\begin{aligned} h |a| &= f a \\ h (x \ominus y) &= h x \oplus h y \\ h (x \oplus y) &= h x \otimes h y \end{aligned}$$

For notational convenience, we write  $(\langle f, \oplus, \otimes \rangle)$  to denote  $h$ . When it is clear from the context, we just call  $(\langle f, \oplus, \otimes \rangle)$  homomorphism.

Intuitively, a homomorphism  $(f, \oplus, \otimes)$  is a function to replace the constructors  $|\cdot|$ ,  $\oplus$  and  $\otimes$  in an input abide tree by  $f$ ,  $\oplus$  and  $\otimes$  respectively. We will see in Section 3 that many algorithms on two-dimensional arrays can be concisely specified by homomorphisms.

It is worth noting that  $\oplus$  and  $\otimes$  in  $(f, \oplus, \otimes)$  should be associative and satisfy the abide property, inheriting the properties of  $\oplus$  and  $\otimes$ .

Homomorphism enjoys many nice transformation rules, among which the following fusion rule is of particular importance. The fusion rule gives us a way to create a new homomorphism from composition of a function and a homomorphism. As will be seen in Section 4, it plays a key role in derivation of efficient parallel programs on abide trees.

**Theorem 2.1 (Fusion)** Let  $h$  and  $(f, \oplus, \otimes)$  be given. If there exist  $\odot$  and  $\ominus$  such that for all  $x$  and  $y$ ,

$$\begin{cases} h(x \oplus y) = h x \odot h y \\ h(x \otimes y) = h x \ominus h y \end{cases}$$

hold, then

$$h \circ (f, \oplus, \otimes) = (h \circ f, \odot, \ominus) .$$

PROOF. The theorem is proved by the induction on the structure of abide trees.

Base case:

$$\begin{aligned} & (h \circ (f, \oplus, \otimes)) |a| \\ = & \quad \{ \text{Definition of } (f, \oplus, \otimes) \} \\ & h(f a) \\ = & \quad \{ \text{Definition of } (h \circ f, \odot, \ominus) \} \\ & (h \circ f, \odot, \ominus) |a| \end{aligned}$$

Induction for  $\oplus$ :

$$\begin{aligned} & (h \circ (f, \oplus, \otimes)) (x \oplus y) \\ = & \quad \{ \text{Definition of } (f, \oplus, \otimes) \} \\ & h((f, \oplus, \otimes) x \oplus (f, \oplus, \otimes) y) \\ = & \quad \{ \text{Definition of } h \} \\ & h((f, \oplus, \otimes) x) \odot h((f, \oplus, \otimes) y) \\ = & \quad \{ \text{Hypothesis of induction} \} \\ & (h \circ f, \odot, \ominus) x \odot (h \circ f, \odot, \ominus) y \\ = & \quad \{ \text{Definition of } (h \circ f, \odot, \ominus) \} \\ & (h \circ f, \odot, \ominus) (x \oplus y) \end{aligned}$$

Induction for  $\otimes$  is proved similarly.  $\square$

A homomorphism  $(f, \oplus, \otimes)$  can be implemented *efficiently* in parallel, which will be shown in Section 5. Let  $N$  be the number of elements in a two-dimensional array,  $T_f, T_\oplus, T_\otimes$  be the parallel time cost for computing  $f$ ,  $\oplus$  and  $\otimes$  respectively. Then,  $(f, \oplus, \otimes)$  takes parallel time of  $T_f \times O(\log N) \times \max(T_\oplus, T_\otimes)$  with enough number of processors.

### 2.3 Almost-Homomorphism

Not all functions can be specified by a single homomorphism, but we can always tuple these functions with some extra functions so that the tupled functions can be specified by a homomorphism. An *almost homomorphism*, as discussed in [8], is a composition of a projection function and a homomorphism. Since projection functions are simple, almost homomorphisms are suitable for parallel computation as homomorphisms are.

In fact, every function can be represented in terms of an almost homomorphism. Let  $k$  be a nonhomomorphic function, and consider a new function  $g$  such that  $g x = (k x, x)$ . The tupled function  $g$  is a homomorphism.

$$\begin{aligned} g |a| &= (k |a|, |a|) \\ g (x \oplus y) &= g x \oplus g y \\ &\quad \textbf{where } (k_1, x_1) \oplus (k_2, x_2) = (k (x_1 \oplus x_2), x_1 \oplus x_2) \\ g (x \phi y) &= g x \otimes g y \\ &\quad \textbf{where } (k_1, x_1) \otimes (k_2, x_2) = (k (x_1 \phi x_2), x_1 \phi x_2) \end{aligned}$$

Then,  $k$  is written as an almost homomorphism:

$$k = \pi_1 \circ g = \pi_1 \circ (|g \circ |\cdot|, \oplus, \otimes) .$$

However, the definition above is not efficient because binary operators  $\oplus$  and  $\otimes$  do not use the previously computed values  $k_1$  and  $k_2$ . In order to derive a good almost homomorphism, we should carefully define a suitable tupled function, making full use of previously computed values. We will see this in our parallel program development in Section 4.

### 3. PARALLEL ALGORITHMS ON TWO-DIMENSIONAL ARRAYS

Homomorphisms are suitable for parallel implementation, which has been argued in the previous section and will be detailed in Section 5. In this section, we show that homomorphisms are powerful enough to describe many useful parallel algorithms for manipulating two-dimensional arrays. We will start by demonstrating that basic parallel computation components, namely basic data parallel skeletons and basic communication skeletons, can be specified by either homomorphisms or recursions on the abide trees, and then we show that composition of these basic parallel skeletons is powerful enough to solve nontrivial problems such as matrix multiplication and QR decomposition.

#### 3.1 Data Parallel Skeletons

We define four primitive functions `map`, `reduce`, `zipwith` and `scan` on the data type *AbideTree*. In the theory of Constructive Algorithmics [4, 30, 2], these functions are known to be the most fundamental computation components for manipulating algebraic data structures and for being glued together to express complicated computations. We call them *data parallel skeletons* because they have potential parallelism and can be implemented efficiently in parallel (see Section 5.)

##### **Map and Reduce**

The skeletons `map` and `reduce` are two special cases of homomorphism. The skeleton `map` applies a function  $f$  to each element of a two-dimensional array while keeping the structure, and is defined by

$$\begin{aligned} \text{map } f |a| &= |f a| \\ \text{map } f (x \oplus y) &= (\text{map } f x) \oplus (\text{map } f y) \\ \text{map } f (x \phi y) &= (\text{map } f x) \phi (\text{map } f y) , \end{aligned}$$

that is,  $\text{map } f = (|\cdot| \circ f, \oplus, \phi)$  .

The skeleton `reduce` collapses a two-dimensional array to a value using two abiding binary operators  $\oplus$ ,  $\otimes$ , and is defined by

$$\begin{aligned} \text{reduce}(\oplus, \otimes) |a| &= a \\ \text{reduce}(\oplus, \otimes) (x \oplus y) &= (\text{reduce}(\oplus, \otimes) x) \oplus (\text{reduce}(\oplus, \otimes) y) \\ \text{reduce}(\oplus, \otimes) (x \phi y) &= (\text{reduce}(\oplus, \otimes) x) \otimes (\text{reduce}(\oplus, \otimes) y) , \end{aligned}$$

that is,  $\text{reduce}(\oplus, \otimes) = (id, \oplus, \otimes)$  .



Interestingly, any homomorphism  $(f, \oplus, \otimes)$  can be written as a composition of `map` and `reduce`, i.e.

$$(f, \oplus, \otimes) = \text{reduce}(\oplus, \otimes) \circ \text{map } f$$

which implies that if we have efficient parallel implementations for `reduce` and `map`, we get an efficient implementation for homomorphism.

### **Zipwith**

The two skeletons defined above are primitive skeletons. We define other skeletons which are extensions of these primitive skeletons. The skeleton `zipwith`, an extension of `map`, takes two two-dimensional arrays of the same shape, applies a function  $f$  to corresponding elements of the arrays and returns a new array of the same shape.

$$\begin{aligned} \text{zipwith } f \ |a| \ |b| &= |f \ a \ b| \\ \text{zipwith } f \ (x \ominus y) \ (u \ominus v) &= (\text{zipwith } f \ x \ u) \ominus (\text{zipwith } f \ y \ v) \\ \text{zipwith } f \ (x \oplus y) \ (u \oplus v) &= (\text{zipwith } f \ x \ u) \oplus (\text{zipwith } f \ y \ v) \end{aligned}$$

Note that in the above definition two-dimensional arrays which are the arguments of the function should be divided in the way that the sizes of  $x$  and  $u$  are the same. Function `zip` is a specialization of `zipwith`, making a two-dimensional array of pairs of corresponding elements.

$$\text{zip}(u, v) = \text{zipwith}(\lambda xy. (x, y)) \ u \ v$$

We may define similar `zip` and `zipwith` for the case when the number of input arrays is three or more, and those which take  $k$  arrays are denoted by `zipk` and `zipwithk`. Also we define `unzip` to be the inverse of `zip`.

With these three skeletons defined above, we are able to describe many useful functions.

$$\begin{aligned} id &= \text{reduce}(\ominus, \oplus) \circ \text{map} \ |\cdot| \\ tr &= \text{reduce}(\phi, \ominus) \circ \text{map} \ |\cdot| \\ rev &= \text{reduce}(\tilde{\ominus}, \tilde{\oplus}) \circ \text{map} \ |\cdot| \\ flatten &= \text{reduce}(\ominus, \phi) \\ height &= \text{reduce}(+, \ll) \circ \text{map} \ (\lambda x. 1) \\ width &= \text{reduce}(\ll, +) \circ \text{map} \ (\lambda x. 1) \\ cols &= \text{reduce}(\text{zipwith}(\ominus), \phi) \circ \text{map} \ ||\cdot|| \\ rows &= \text{reduce}(\ominus, \text{zipwith}(\phi)) \circ \text{map} \ ||\cdot|| \\ \text{reduce}_c(\oplus) &= \text{map}(\text{reduce}(\oplus, \ll)) \circ cols \\ \text{reduce}_r(\otimes) &= \text{map}(\text{reduce}(\ll, \otimes)) \circ rows \\ \text{map}_c f &= \text{reduce}(\ll, \phi) \circ \text{map } f \circ cols \\ \text{map}_r f &= \text{reduce}(\ominus, \ll) \circ \text{map } f \circ rows \\ add &= \text{zipwith}(+) \\ sub &= \text{zipwith}(-) \end{aligned}$$

Note that `||·||` is abbreviation of `|\cdot| \circ |\cdot|`; `id` is the identity function of *AbideTree*; `tr` is the matrix-transposing function; `rev` takes a two-dimensional array and returns the array reversed in the vertical and the horizontal direction; `flatten` flattens a nested *AbideTree*; `height` and `width` return the number of rows and columns respectively, `cols` and `rows` return an array of which elements are columns and rows of the array of the argument respectively; `reducec` and `reducer` which are specializations of `reduce` reduce a two-dimensional array in each column and row direction respectively and return a row-vector (an array of which height is one) and a column-vector (an array of which width is one); `mapc` and `mapr` which are specializations of `map` apply a function to each column and row respectively (i.e. the function of the argument takes column-vector or row-vector); and `add` and `sub` denote matrix addition and subtraction respectively.

## Scan

The skeleton `scan`, an extension of `reduce`, holds all values generated in reducing a two-dimensional array by `reduce`.

$$\begin{aligned} \text{scan}(\oplus, \otimes) |a| &= |a| \\ \text{scan}(\oplus, \otimes)(x \ominus y) &= (\text{scan}(\oplus, \otimes) x) \oplus' (\text{scan}(\oplus, \otimes) y) \\ \text{scan}(\oplus, \otimes)(x \oplus y) &= (\text{scan}(\oplus, \otimes) x) \otimes' (\text{scan}(\oplus, \otimes) y) \end{aligned}$$

Here two binary operators  $\oplus'$  and  $\otimes'$  are defined as follows.

$$\begin{aligned} \text{bottom} &= \text{reduce}(\gg, \phi) \circ \text{map} |\cdot| \\ \text{last} &= \text{reduce}(\ominus, \gg) \circ \text{map} |\cdot| \\ \text{sx} \oplus' \text{sy} &= \text{sx} \ominus \text{sy}' \\ &\quad \textbf{where } \text{sy}' = \text{map}_r(\text{zipwith}(\oplus)(\text{bottom } \text{sx})) \text{sy} \\ \text{sx} \otimes' \text{sy} &= \text{sx} \oplus \text{sy}' \\ &\quad \textbf{where } \text{sy}' = \text{map}_c(\text{zipwith}(\otimes)(\text{last } \text{sx})) \text{sy} \end{aligned}$$

It should be noted that `reduce` can be expressed by `reducec` and `reducer` when two binary operators  $\oplus$  and  $\otimes$  are abiding.

$$\begin{aligned} \text{reduce}(\oplus, \otimes) &= \text{the} \circ \text{reduce}_c(\oplus) \circ \text{reduce}_r(\otimes) \\ \text{reduce}(\oplus, \otimes) &= \text{the} \circ \text{reduce}_r(\otimes) \circ \text{reduce}_c(\oplus) \end{aligned} \quad (1)$$

Like `reduce`, we may define `scan↓` and `scan→` which are specialization of `scan` and `scan` a two-dimensional array in each column and row direction respectively:

$$\begin{aligned} \text{scan}_\downarrow(\oplus) &= \text{scan}(\oplus, \gg) \\ \text{scan}_\rightarrow(\otimes) &= \text{scan}(\gg, \otimes); \end{aligned}$$

`scan` can be expressed by `scan↓` and `scan→` when two binary operators  $\oplus$  and  $\otimes$  are abiding.

$$\begin{aligned} \text{scan}(\oplus, \otimes) &= \text{scan}_\downarrow(\oplus) \circ \text{scan}_\rightarrow(\otimes) \\ \text{scan}(\oplus, \otimes) &= \text{scan}_\rightarrow(\otimes) \circ \text{scan}_\downarrow(\oplus) \end{aligned} \quad (2)$$

Using the skeleton `scan`, we can define `scanr` which executes `scan` reversely, `allredr` and `allredc` which broadcast the results in each row and column after `reducer` and `reducec` respectively. These functions are used in later section.

$$\begin{aligned} \text{scanr}(\oplus, \otimes) &= \text{rev} \circ \text{scan}(\tilde{\oplus}, \tilde{\otimes}) \circ \text{rev} \\ \text{allred}_c(\oplus) &= \text{scanr}(\gg, \ll) \circ \text{scan}(\oplus, \gg) \\ \text{allred}_r(\otimes) &= \text{scanr}(\ll, \gg) \circ \text{scan}(\gg, \otimes) \end{aligned}$$

## 3.2 Data Communication Skeletons

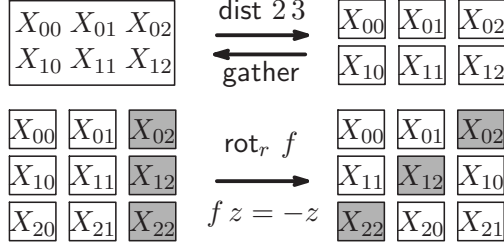
We show how to define data communication skeletons `dist`, `gather`, `rotr` and `rotc` which abstract distribution, collection and rearrangement of a two-dimensional array among processors. The idea is to use nested two-dimensional arrays to represent distributed two-dimensional arrays.

The skeleton `dist` abstracts distribution of a two-dimensional array to processors, and is defined as

$$\begin{aligned} \text{dist } p \ q \ x &= (\text{flatten} \circ \text{map}(\text{grp}_c n) \circ \text{grp}_r m) x \\ &\quad \textbf{where } m = \lceil \text{height } x / p \rceil, \ n = \lceil \text{width } x / q \rceil \end{aligned}$$

where `grpr` is defined as follows and `grpc` is defined similarly.

$$\begin{aligned} \text{grp}_r k (x \ominus y) &= |x| \ominus (\text{grp}_r k y) \quad \text{if } \text{height } x = k \\ \text{grp}_r k x &= |x| \quad \text{if } \text{height } x < k \end{aligned}$$



**Figure 1: An image of communication skeletons** (each rectangle corresponds to each processor;  $X_{ij}$  represents a subarray.)

The skeleton `gather`, the inverse operator of `dist`, abstracts gathering of two-dimensional arrays distributed to the processors into a two-dimensional array on the root processor.

$$\text{gather} = \text{reduce}(\ominus, \phi)$$

Although definitions of these skeletons may seem complicated, actual operations are rather simple as illustrated in Figure 1. What is significant here is that these skeletons satisfy the relation of  $id = \text{gather} \circ \text{dist} \circ pq$ .

The rotation skeleton `rotr` which takes a function  $f$  and rotates  $i$ -th row (the index begins from 0) by  $f i$ , is defined as follows:

$$\text{rot}_r f = \text{flatten} \circ \text{map } \text{shift}_r \circ \text{addidx}_r \circ \text{rows}$$

where

$$\text{addidx}_r u = \text{zip}(\text{map } f (\text{idx}_r u), u)$$

$$\text{idx}_r = \text{map}(-1) \circ \text{scan}_1(+) \circ \text{map}(\lambda x. 1) \quad ;$$

here  $\text{shift}_r$  is defined under the condition  $i > 0$  below.

$$\begin{aligned} \text{shift}_r(0, x) &= x \\ \text{shift}_r(i, x \oplus y) &= y \oplus x \quad \text{if width } y = i \\ \text{shift}_r(-i, x \oplus y) &= y \oplus x \quad \text{if width } x = i \end{aligned}$$

Similarly, we can define the skeleton `rotc` which takes a function  $f$  and rotates  $i$ -th column by  $f i$ . An image of the above communication skeletons is depicted in Figure 1. In the figure, since the rotation skeleton `rotr` takes a negation function, 0-th row does not rotate (rotates by 0), first row rotates to the left by 1 (to the right by  $-1$ ) and second row rotates to the left by 2 (to the right by  $-2$ ).

### 3.3 Matrix Multiplication

As a more involved example, we describe two known parallel algorithms for matrix multiplication, which is a primitive operation of matrices, in terms of the above defined parallel skeletons on two-dimensional arrays.

The first description is of Cannon's Algorithm [16]:

$$mm_C = \text{gather} \circ (\text{map } \text{thd}) \circ (\text{iter } p \text{ step}) \circ \text{zip}_3 \circ \text{arrange} \circ \text{distribute} \circ \text{init}$$

where

$$\text{init}(A, B) = (A, B, \text{map}(\lambda x. 0) A)$$

$$\text{distribute} = (\text{dist } pp \times \text{dist } pp \times \text{dist } pp)$$

$$\text{arrange} = (\text{rot}_r \text{ neg} \times \text{rot}_c \text{ neg} \times id)$$

$$\text{step} = \text{zip}_3 \circ \text{rearrange} \circ \text{unzip}_3 \circ \text{map } lmm$$

$$\text{rearrange} = \text{rot}_r(\lambda x. 1) \times \text{rot}_c(\lambda x. 1) \times id$$

$$\text{neg } x = -x$$

$$\text{thd } (x, y, z) = z$$

where  $p$  is a natural number indicating the number of division of matrices in column and row direction, and  $lmm$  is a function which executes locally matrix multiplication on matrices on each processor, i.e.  $lmm(A, B, C) = (A, B, C + A \times B)$ . The function  $iter$  is defined as follows.

$$\begin{aligned} iter\ k\ f\ x &= x && \text{if } k = 0 \\ iter\ k\ f\ x &= iter\ (k - 1)\ f\ (f\ x) && \text{if } k > 0 \end{aligned}$$

Explicit distribution of matrices by data communication skeletons makes this description looking complicated. However, it should be noted that even non-intuitive complicated Cannon's Algorithm can be described by composition of the skeletons.

The second description is an intuitively understandable description using only data parallel skeletons. This description describes just a definition of matrix multiplication. Although users do not need to take parallelism into consideration at all, this program can be executed in parallel due to parallelism of each skeleton.

$$\begin{aligned} mm &= zipwith_P\ iprod \circ (id \times map\ tr) \circ (allrows \times allcols) \\ \text{where} \\ allrows &= allred_r(\phi) \circ map\ |\cdot| \\ allcols &= allred_c(\oplus) \circ map\ |\cdot| \\ iprod &= (reduce(\ll, +) \circ) \circ zipwith(\times) \\ zipwith_P(\otimes)(x, y) &= zipwith(\otimes)\ x\ y \end{aligned}$$

### 3.4 QR Factorization

As the final nontrivial example, we show descriptions of two parallel algorithms for QR factorization [11]. We will not explain the details, rather we hope to show that these algorithms can be dealt with in our framework.

We give the recursive description of QR factorization algorithm based on Householder transform. This function returns  $Q$  and  $R$  which satisfy  $A = QR$  where  $A$  is a matrix of  $m \times n$ ,  $Q$  an orthogonal matrix of  $m \times m$  and  $R$  an upper-triangular matrix of  $m \times n$ .

$$\begin{aligned} qr\ ((A_{11} \oplus A_{21}) \phi (A_{12} \oplus A_{22})) \\ &= \mathbf{let}\ (Q_1, R_{11} \oplus 0) = qr\ (A_{11} \oplus A_{21}) \\ &\quad (R_{12} \oplus \hat{A}_{22}) = mm\ (tr\ Q_1)\ (A_{12} \oplus A_{22}) \\ &\quad (\hat{Q}_2, R_{22}) = qr\ \hat{A}_{22} \\ &\quad Q = mm\ Q_1\ ((I \phi 0) \oplus (0 \phi \hat{Q}_2)) \\ &\quad \mathbf{in}\ (Q, (R_{11} \phi R_{12}) \oplus (0 \phi R_{22})) \\ qr\ (|a| \oplus x) &= hh\ (|a| \oplus x) \\ hh\ v &= \mathbf{let}\ v' = add\ v\ e \\ &\quad a = \sqrt{reduce(+, +)\ (zipwith(\times)\ v'\ v')} \\ &\quad u = map\ (/a)\ v' \\ &\quad Q = sub\ I\ (map\ (\times 2)\ (mm\ u\ (tr\ u))) \\ &\quad \mathbf{in}\ (Q, e) \end{aligned}$$

Here  $e$  is a vector (a matrix of which width is 1) whose first element is 1 and the other elements are 0, and  $I$  and  $0$  represent an identity matrix and a zero matrix of suitable size respectively.

Furthermore, we give the recursive description of QR factorization algorithm on quadtree [12]; transforming algorithms on quadtrees to those on abide trees is always possible because abide trees is more flexible than quadtrees. This function  $qr_q$  is mutual recursively defined with an extra function  $e$ , and returns  $Q$  and  $R$  which satisfy  $A = QR$  where  $A$  is a matrix of  $n \times n$  ( $n = 2^k$  for a natural number  $k$ ),  $Q$  an orthogonal matrix of  $n \times n$  and  $R$  an upper-triangular

matrix of  $n \times n$ .

$$\begin{aligned}
qr_q |a| &= (|1|, |a|) \\
qr_q ((A_{11} \oplus A_{21}) \oplus (A_{12} \oplus A_{22})) \\
&= \mathbf{let} \ (Q_1, R_1) = qr_q \ A_{11} \\
&\quad (Q_2, R_2) = qr_q \ A_{21} \\
&\quad Q_{12} = (Q_1 \oplus 0) \oplus (0 \oplus Q_2) \\
&\quad (Q_3, R_3) = e \ (R_1, R_2) \\
&\quad Q_4 = mm \ Q_{12} \ Q_3 \\
&\quad (U_n \oplus U_s) = mm \ (tr \ Q_4) \ (A_{12} \oplus A_{22}) \\
&\quad (Q_6, R_6) = qr_q \ U_s \\
&\quad Q = mm \ Q_4 \ ((I \oplus 0) \oplus (0 \oplus Q_6)) \\
&\quad R = (R_3 \oplus U_n) \oplus (0 \oplus R_6) \\
&\mathbf{in} \ (Q, R)
\end{aligned}$$

Note that  $A_{ij}$  ( $i, j \in \{1, 2\}$ ) have the same shape.

$$\begin{aligned}
e \ (N, 0) &= (I, N) \\
e \ (|n|, |s|) &= \mathbf{let} \ Q = g(n, s) \\
&\quad (N, 0) = mm(tr \ Q) \ (|n| \oplus |s|) \\
&\quad \mathbf{in} \ (Q, N) \\
e \ ((N_{11} \oplus N_{21}) \oplus (N_{12} \oplus N_{22}), (S_{11} \oplus S_{21}) \oplus (S_{12} \oplus S_{22})) \\
&= \mathbf{let} \\
&\quad ((Q_1^{11} \oplus Q_1^{21}) \oplus (Q_1^{12} \oplus Q_1^{22}), N_1) = e \ (N_{11}, S_{11}) \\
&\quad ((Q_2^{11} \oplus Q_2^{21}) \oplus (Q_2^{12} \oplus Q_2^{22}), N_2) = e \ (N_{22}, S_{22}) \\
&\quad Q_{12} = (Q_1^{11} \oplus 0 \oplus Q_1^{12} \oplus 0) \oplus (0 \oplus Q_2^{11} \oplus 0 \oplus Q_2^{12}) \\
&\quad \quad \oplus (Q_1^{21} \oplus 0 \oplus Q_1^{22} \oplus 0) \oplus (0 \oplus Q_2^{21} \oplus 0 \oplus Q_2^{22}) \\
&\quad Q_1 = (Q_1^{11} \oplus Q_1^{21}) \oplus (Q_1^{12} \oplus Q_1^{22}) \\
&\quad (U_n \oplus U_s) = mm \ (tr \ Q_1) \ (N_{12} \oplus S_{12}) \\
&\quad (Q_4, R_4) = qr_q \ U_s \\
&\quad Q'_4 = (I \oplus 0 \oplus 0 \oplus 0) \oplus (0 \oplus I \oplus 0 \oplus 0) \oplus (0 \oplus 0 \oplus Q_4 \oplus 0) \oplus (0 \oplus 0 \oplus 0 \oplus I) \\
&\quad Q_5 = mm \ Q_{12} \ Q_4' \\
&\quad ((Q_6^{11} \oplus Q_6^{21}) \oplus (Q_6^{12} \oplus Q_6^{22}), N_6) = e \ (N_2, R_4) \\
&\quad Q'_6 = (I \oplus 0 \oplus 0 \oplus 0) \oplus (0 \oplus Q_6^{11} \oplus Q_6^{12} \oplus 0) \oplus (0 \oplus Q_6^{21} \oplus Q_6^{22} \oplus 0) \oplus (0 \oplus 0 \oplus 0 \oplus I) \\
&\quad \mathbf{in} \ (mm \ Q_5 \ Q'_6, (N_1 \oplus U_n) \oplus (0 \oplus N_6)) \\
g \ (a, b) &= (|c| \oplus |s|) \oplus (|-s| \oplus |c|) \\
&\quad \mathbf{where} \ c = \frac{a}{\sqrt{a^2 + b^2}}, \ s = \frac{-b}{\sqrt{a^2 + b^2}}
\end{aligned}$$

Note that  $N_{ij}$  and  $S_{ij}$  ( $i, j \in \{1, 2\}$ ) have the same shape and  $Q_k^{ij}$  ( $i, j, k \in \{1, 2\}$ ) have the same shape.

Like in [12], we can efficiently parallelize some parts of these complicated recursive functions, such as matrix multiplication in the recursion. It is, however, still an open problem whether the complicated recursive functions can be parallelized, which is one of our future work.

#### 4. DEVELOPING EFFICIENT PARALLEL PROGRAMS

It has been shown so far that compositions of recursive functions on abide trees provide us with a powerful mechanism to describe parallel algorithms on two-dimensional arrays, where parallelism in the original parallel algorithms can be fully captured. In this section, we move on from issues of parallelism to the issues of efficiency. We shall illustrate a strategy to guide programmers to systematically develop *efficient* parallel algorithms through program transformation. Remember (almost-) homomorphisms have efficient parallel implementation as composition of our parallel skeletons.

Our strategy for deriving efficient parallel programs on two-dimensional arrays consists of the following four steps, extending the result of [18].

- Step 1. Define the target program  $p$  as a composition of  $p_1, \dots, p_n$  which are already defined, i.e.  $p = p_n \circ \dots \circ p_1$ . Each of  $p_1, \dots, p_n$  may be defined as a composition of small functions or a recursive function (see Section 3.3 and Section 3.4).
- Step 2. Derive an almost homomorphism (Section 2.3) from the recursive definition of  $p_1$ .
- Step 3. Fuse  $p_2$  into the derived almost homomorphism to obtain a new almost homomorphism for  $p_2 \circ p_1$ , and repeat this derivation until  $p_n$  is fused.
- Step 4. Let  $\pi_1 \circ (|f, \oplus, \otimes|)$  be the resulting almost homomorphism for  $p_n \circ \dots \circ p_1$  obtained at Step 3. For the functions inside the homomorphism, namely  $f$ ,  $\oplus$  and  $\otimes$ , try to repeat Steps 2 and 3 to find efficient parallel implementations for them.

In the following, we explain this strategy through a derivation of an efficient program for the maximum rectangle sum problem: compute the maximum of sums of all the rectangle data areas in a two-dimensional data. For example, for the following two-dimensional data

$$\begin{pmatrix} 3 & -1 & \mathbf{4} & -1 & -5 \\ 1 & -4 & -1 & \mathbf{5} & -3 \\ -4 & 1 & \mathbf{5} & \mathbf{3} & 1 \end{pmatrix}$$

the result should be 15, which denotes the maximum sum contributed by the sub-rectangular area with bolded numbers above. To appreciate difficulty of this problem, we ask the reader to pause for a while to think how you solve it.

### Step 1. Defining a Clear Parallel Program

A clear and straightforward solution to the maximum rectangle sum problem is as follows: enumerating all possible rectangles, then computing sums for all rectangles, and finally returning the maximum value as the result.

$$\begin{aligned} mrs &= \text{max} \circ \text{map} \text{ max} \circ \text{map} (\text{map sum}) \circ \text{rects} \\ \text{where} \\ \text{max} &= \text{reduce}(\uparrow, \uparrow) \\ \text{sum} &= \text{reduce}(+, +) \end{aligned}$$

Here  $\text{rects}$  is a function which takes a two-dimensional array and returns all possible rectangles of the array. The returned value of  $\text{rects}$  is an array of arrays of arrays, and  $(k, l)$ -element of  $(i, j)$ -element of the resulting array is a sub-rectangle having rows from  $i$ -th to  $j$ -th and columns from  $k$ -th to  $l$ -th of the original array. An example of  $\text{rects}$  is shown below. Note that we think that the special value is contained in the blank portion of the above-mentioned array, and we write the blank of arbitrary size by  $NIL$  for brevity. In this case,  $NIL$  may be an array of which element is  $-\infty$  or an array of it.

$$\text{rects} \begin{pmatrix} 1 & 2 & 3 \\ 5 & 6 & 7 \end{pmatrix} = \left( \begin{pmatrix} (1) & (1 \ 2) & (1 \ 2 \ 3) \\ (2) & (2 \ 3) & \\ (3) & & \end{pmatrix} \begin{pmatrix} \begin{pmatrix} (1) \\ (5) \end{pmatrix} & \begin{pmatrix} (1 \ 2) \\ (5 \ 6) \end{pmatrix} & \begin{pmatrix} (1 \ 2 \ 3) \\ (5 \ 6 \ 7) \end{pmatrix} \\ (2) & (2 \ 3) & \\ (3) & & \end{pmatrix} \right)$$

The function *rects* is mutual recursively defined as follows:

$$\begin{aligned}
\mathit{rects} \ |a| &= |||a||| \\
\mathit{rects} (x \oplus y) &= (\mathit{rects} \ x \ \phi \ \mathit{gemm}(\_, \mathit{zipwith}(\oplus)) \ (\mathit{bottoms} \ x) \ (\mathit{tops} \ y)) \ \oplus \ (\mathit{NIL} \ \phi \ \mathit{rects} \ y) \\
\mathit{rects} (x \ \phi \ y) &= \mathit{zipwith}_4 \ f_s \ (\mathit{rects} \ x) \ (\mathit{rects} \ y) \ (\mathit{rights} \ x) \ (\mathit{lefts} \ y) \\
&\quad \mathbf{where} \ f_s \ s_1 \ s_2 \ r_1 \ l_2 = (s_1 \ \phi \ \mathit{gemm}(\_, \phi) \ r_1 \ l_2) \ \oplus \ (\mathit{NIL} \ \phi \ s_2)
\end{aligned}$$

where ‘\_’ indicates “don’t care” and generalized matrix multiplication *gemm* is defined as follows:

$$\begin{aligned}
\mathit{gemm}(\oplus, \otimes) &= g \\
\mathbf{where} \\
g (X_1 \ \phi \ X_2) (Y_1 \ \oplus \ Y_2) &= \mathit{zipwith}(\oplus) (g \ X_1 \ Y_1) (g \ X_2 \ Y_2) \\
g (X_1 \ \oplus \ X_2) Y &= (g \ X_1 \ Y) \ \oplus \ (g \ X_2 \ Y) \\
g X (Y_1 \ \phi \ Y_2) &= (g \ X \ Y_1) \ \phi \ (g \ X \ Y_2) \\
g |a| |b| &= |a \ \otimes \ b|
\end{aligned}$$

Functions *bottoms*, *tops*, *rights* and *lefts* are similarly defined as mutual recursive functions with some extra functions:

$$\begin{aligned}
\mathit{tops} \ |a| &= |||a||| \\
\mathit{tops} (x \ \oplus \ y) &= \mathit{tops} \ x \ \phi \ \mathit{map} \ (\mathit{zipwith}(\oplus) \ (\mathit{cols}' \ x)) \ (\mathit{tops} \ y) \\
\mathit{tops} (x \ \phi \ y) &= \mathit{zipwith}_4 \ f_t \ (\mathit{tops} \ x) \ (\mathit{tops} \ y) \ (\mathit{toprights} \ x) \ (\mathit{tolefts} \ y) \\
&\quad \mathbf{where} \ f_t \ t_1 \ t_2 \ tr_1 \ tl_2 = (t_1 \ \phi \ \mathit{gemm}(\_, \phi) \ tr_1 \ tl_2) \ \oplus \ (\mathit{NIL} \ \phi \ t_2) \\
\mathit{bottoms} \ |a| &= |||a||| \\
\mathit{bottoms} (x \ \oplus \ y) &= \mathit{map} \ (\lambda z \rightarrow \mathit{zipwith}(\oplus) \ z \ (\mathit{cols}' \ y)) \ (\mathit{bottoms} \ x) \ \oplus \ \mathit{bottoms} \ y \\
\mathit{bottoms} (x \ \phi \ y) &= \mathit{zipwith}_4 \ f_b \ (\mathit{bottoms} \ x) \ (\mathit{bottoms} \ y) \ (\mathit{bottomrights} \ x) \ (\mathit{bottomlefts} \ y) \\
&\quad \mathbf{where} \ f_b \ b_1 \ b_2 \ br_1 \ bl_2 = (b_1 \ \phi \ \mathit{gemm}(\_, \phi) \ br_1 \ bl_2) \ \oplus \ (\mathit{NIL} \ \phi \ b_2) \\
\mathit{rights} \ |a| &= |||a||| \\
\mathit{rights} (x \ \oplus \ y) &= (\mathit{rights} \ x \ \phi \ \mathit{gemm}(\_, \mathit{zipwith}(\oplus)) \ (\mathit{bottomrights} \ x) \ (\mathit{toprights} \ y)) \\
&\quad \oplus \ (\mathit{NIL} \ \phi \ \mathit{rights} \ y) \\
\mathit{rights} (x \ \phi \ y) &= \mathit{zipwith}_3 \ f_r \ (\mathit{rights} \ x) \ (\mathit{rights} \ y) \ (\mathit{rows}' \ y) \\
&\quad \mathbf{where} \ f_r \ r_1 \ r_2 \ ro_2 = \mathit{map} \ (\phi \ ro_2) \ r_1 \ \oplus \ r_2 \\
\mathit{lefts} \ |a| &= |||a||| \\
\mathit{lefts} (x \ \oplus \ y) &= (\mathit{lefts} \ x \ \phi \ \mathit{gemm}(\_, \mathit{zipwith}(\oplus)) \ (\mathit{bottomlefts} \ x) \ (\mathit{tolefts} \ y)) \ \oplus \ (\mathit{NIL} \ \phi \ \mathit{lefts} \ y) \\
\mathit{lefts} (x \ \phi \ y) &= \mathit{zipwith}_3 \ f_l \ (\mathit{lefts} \ x) \ (\mathit{lefts} \ y) \ (\mathit{rows}' \ x) \\
&\quad \mathbf{where} \ f_l \ l_1 \ l_2 \ ro_1 = l_1 \ \phi \ \mathit{map} \ (ro_1 \ \phi) \ l_2 \\
\mathit{toprights} \ |a| &= |||a||| \\
\mathit{toprights} (x \ \oplus \ y) &= \mathit{toprights} \ x \ \phi \ \mathit{map} \ (\mathit{zipwith}(\oplus) \ (\mathit{right}' \ (\mathit{toprights} \ x))) \ (\mathit{toprights} \ y) \\
\mathit{toprights} (x \ \phi \ y) &= \mathit{zipwith} \ f_{tr} \ (\mathit{toprights} \ x) \ (\mathit{toprights} \ y) \\
&\quad \mathbf{where} \ f_{tr} \ tr_1 \ tr_2 = \mathit{map} \ (\phi \ \mathit{top}' \ tr_2 \ \phi) \ tr_1 \ \oplus \ tr_2 \\
\mathit{bottomrights} \ |a| &= |||a||| \\
\mathit{bottomrights} (x \ \oplus \ y) &= \mathit{map} \ (\lambda z \rightarrow \mathit{zipwith}(\oplus) \ z \ (\mathit{top}' \ (\mathit{bottomrights} \ y))) \ (\mathit{bottomrights} \ x) \\
&\quad \oplus \ \mathit{bottomrights} \ y \\
\mathit{bottomrights} (x \ \phi \ y) &= \mathit{zipwith} \ f_{br} \ (\mathit{bottomrights} \ x) \ (\mathit{bottomrights} \ y) \\
&\quad \mathbf{where} \ f_{br} \ br_1 \ br_2 = \mathit{map} \ (\phi \ \mathit{top}' \ br_2 \ \phi) \ br_1 \ \oplus \ br_2
\end{aligned}$$

$$\begin{aligned}
\text{toplefts } |a| &= |||a||| \\
\text{toplefts } (x \oplus y) &= \text{toplefts } x \oplus \text{map } (\text{zipwith}(\oplus) (\text{right}' (\text{toplefts } x))) (\text{toplefts } y) \\
\text{toplefts } (x \oplus y) &= \text{zipwith } f_{tl} (\text{toplefts } x) (\text{toplefts } y) \\
&\quad \text{where } f_{tl} \text{ } tl_1 \text{ } tl_2 = tl_1 \oplus \text{map } (\text{right}' \text{ } tl_1 \oplus) \text{ } tl_2 \\
\text{bottomlefts } |a| &= |||a||| \\
\text{bottomlefts } (x \oplus y) &= \text{map } (\lambda z \rightarrow \text{zipwith}(\oplus) z (\text{top}' (\text{bottomlefts } y))) (\text{bottomlefts } x) \\
&\quad \oplus \text{bottomlefts } y \\
\text{bottomlefts } (x \oplus y) &= \text{zipwith } f_{bl} (\text{bottomlefts } x) (\text{bottomlefts } y) \\
&\quad \text{where } f_{bl} \text{ } bl_1 \text{ } bl_2 = bl_1 \oplus \text{map } (\text{right}' \text{ } bl_1 \oplus) \text{ } bl_2 \\
\text{cols}' |a| &= ||a|| \\
\text{cols}' (x \oplus y) &= \text{zipwith}(\oplus) (\text{cols}' x) (\text{cols}' y) \\
\text{cols}' (x \oplus y) &= (\text{cols}' x \oplus \text{gemm } (\_, \oplus) (\text{right} (\text{cols}' x)) (\text{top} (\text{cols}' y))) \oplus (\text{NIL} \oplus \text{cols}' y) \\
\text{rows}' |a| &= ||a|| \\
\text{rows}' (x \oplus y) &= (\text{rows}' x \oplus \text{gemm } (\_, \oplus) (\text{right} (\text{rows}' x)) (\text{top} (\text{rows}' y))) \oplus (\text{NIL} \oplus \text{rows}' y) \\
\text{rows}' (x \oplus y) &= \text{zipwith}(\oplus) (\text{rows}' x) (\text{rows}' y) \\
\text{top} &= \text{reduce}(\ll, \oplus) \circ \text{map } |\cdot| \\
\text{bottom} &= \text{reduce}(\gg, \oplus) \circ \text{map } |\cdot| \\
\text{right} &= \text{reduce}(\oplus, \gg) \circ \text{map } |\cdot| \\
\text{left} &= \text{reduce}(\oplus, \ll) \circ \text{map } |\cdot| \\
\text{top}' &= \text{the} \circ \text{top} \\
\text{bottom}' &= \text{the} \circ \text{bottom} \\
\text{right}' &= \text{the} \circ \text{right} \\
\text{left}' &= \text{the} \circ \text{left}
\end{aligned}$$

Although this initial program is clear and has all its parallelism specified in terms of our parallel skeletons, it is inefficient in the sense that it needs to execute  $O(n^6)$  addition operations for the input of  $n \times n$  array. We shall show how to develop a more efficient parallel program.

Examples of these functions are listed in Appendix A.

## Step 2. Deriving Almost Homomorphism

First of all, we propose a way of deriving almost homomorphism from mutual recursive definitions. For notational convenience, we define

$$\begin{aligned}
\Delta_1^n f_i &= f_1 \Delta f_2 \Delta \cdots \Delta f_n \\
x(\Delta_1^n \oplus_i) y &= (x \oplus_1 y, x \oplus_2 y, \dots, x \oplus_n y) .
\end{aligned}$$

Our main idea is based on the following theorem.

### Theorem 4.1 (Tupling)

Let  $h_1, h_2, \dots, h_n$  be mutual recursively defined by

$$\begin{cases}
h_i |a| &= f_i a \\
h_i (x \oplus y) &= ((\Delta_1^n h_i) x) \oplus_i ((\Delta_1^n h_i) y) \\
h_i (x \oplus y) &= ((\Delta_1^n h_i) x) \otimes_i ((\Delta_1^n h_i) y)
\end{cases} \quad (3)$$

Then  $\Delta_1^n h_i$  is a homomorphism  $(\Delta_1^n f_i, \Delta_1^n \oplus_i, \Delta_1^n \otimes_i)$  .

PROOF. The theorem is proven based on the definition of homomorphisms. According to the definition of array homomorphisms, it is sufficient to prove that

$$\begin{aligned}
(\Delta_1^n h_i) |a| &= (\Delta_1^n f_i) a \\
(\Delta_1^n h_i) (x \oplus y) &= ((\Delta_1^n h_i) x) (\Delta_1^n \oplus_i) ((\Delta_1^n h_i) y) \\
(\Delta_1^n h_i) (x \oplus y) &= ((\Delta_1^n h_i) x) (\Delta_1^n \otimes_i) ((\Delta_1^n h_i) y) .
\end{aligned}$$



The first equation is proved by the following calculation.

$$\begin{aligned}
& (\Delta_1^n h_i) |a| \\
= & \{ \text{Definition of } \Delta \} \\
& (h_1 |a|, \dots, h_n |a|) \\
= & \{ \text{Definition of } h_i \} \\
& (f_1 a, \dots, f_n a) \\
= & \{ \text{Definition of } \Delta \} \\
& (\Delta_1^n f_i) a
\end{aligned}$$

The second is proved as follows.

$$\begin{aligned}
& (\Delta_1^n h_i) (x \oplus y) \\
= & \{ \text{Definition of } \Delta \} \\
& (h_1 (x \oplus y), \dots, h_n (x \oplus y)) \\
= & \{ \text{Definition of } h_i \} \\
& (((\Delta_1^n h_i) x) \oplus_1 ((\Delta_1^n h_i) y), \\
& \quad \dots, ((\Delta_1^n h_i) x) \oplus_n ((\Delta_1^n h_i) y)) \\
= & \{ \text{Definition of } \Delta \} \\
& ((\Delta_1^n h_i) x) (\Delta_1^n \oplus_i) ((\Delta_1^n h_i) y)
\end{aligned}$$

The third is proved similarly.  $\square$

Theorem 4.1 says that if  $h_1$  is mutually defined with other functions (i.e.  $h_2, \dots, h_n$ ) which traverse over the same array in the specific form of Eq. (3), then tupling  $h_1, \dots, h_n$  will give a homomorphism. It follows that every  $h_i$  is an almost homomorphism. Thus, this theorem gives us a systematic way to execute Step 2 of the strategy.

We apply this theorem to derive an almost homomorphism for *rects*. In fact *rects* is mutually defined with some other functions such as *tops* and *bottoms*, and these functions are in the form of Eq. (3). Thus, letting  $h_1 = \text{rects}$ ,  $h_2 = \text{tops}$ ,  $h_3 = \text{bottoms}$ ,  $h_4 = \text{rights}$ ,  $h_5 = \text{lefts}$ ,  $h_6 = \text{toprights}$ ,  $h_7 = \text{bottomrights}$ ,  $h_8 = \text{tolefts}$ ,  $h_9 = \text{bottomlefts}$ ,  $h_{10} = \text{cols}'$ ,  $h_{11} = \text{rows}'$ , we can obtain an almost homomorphism for *rects* by tupling these functions as follows.

$$\text{rects} = \pi_1 \circ (\Delta_1^{11} h_i) = \pi_1 \circ ( (\Delta_1^{11} f_i, \Delta_1^{11} \oplus_i, \Delta_1^{11} \otimes_i) )$$

where

$$\begin{aligned}
\Delta_1^{11} f_i |a| &= (|||a|||, |||a|||, |||a|||, |||a|||, |||a|||, |||a|||, |||a|||, |||a|||, |||a|||, |||a|||, |||a|||, |||a|||) \\
(s_1, t_1, b_1, r_1, l_1, tr_1, br_1, tl_1, bl_1, c_1, ro_1) (\Delta_1^{11} \oplus_i) (s_2, t_2, b_2, r_2, l_2, tr_2, br_2, tl_2, bl_2, c_2, ro_2) \\
&= (s_0, t_0, b_0, r_0, l_0, tr_0, br_0, tl_0, bl_0, c_0, ro_0)
\end{aligned}$$

where

$$\begin{aligned}
s_0 &= (s_1 \phi \text{ gemm } (\_, \text{zipwith}(\oplus)) b_1 t_2) \oplus (NIL \phi s_2) \\
t_0 &= t_1 \phi \text{ map } (\text{zipwith}(\oplus) c_1) t_2 \\
b_0 &= \text{map } (\lambda z \rightarrow \text{zipwith}(\oplus) z c_2) b_1 \oplus b_2 \\
r_0 &= (r_1 \phi \text{ gemm } (\_, \text{zipwith}(\oplus)) br_1 tr_2) \oplus (NIL \phi r_2) \\
l_0 &= (l_1 \phi \text{ gemm } (\_, \text{zipwith}(\oplus)) bl_1 tl_2) \oplus (NIL \phi l_2) \\
tr_0 &= tr_1 \phi \text{ map } (\text{zipwith}(\oplus) (\text{right}' tr_1)) tr_2 \\
br_0 &= \text{map } (\lambda z \rightarrow \text{zipwith}(\oplus) z (\text{top}' br_2)) br_1 \oplus br_2 \\
tl_0 &= tl_1 \phi \text{ map } (\text{zipwith}(\oplus) (\text{right}' tl_1)) tl_2 \\
bl_0 &= \text{map } (\lambda z \rightarrow \text{zipwith}(\oplus) z (\text{top}' bl_2)) bl_1 \oplus bl_2 \\
c_0 &= \text{zipwith}(\oplus) c_1 c_2 \\
ro_0 &= (ro_1 \phi \text{ gemm } (\_, \oplus) (\text{right}' ro_1) (\text{top}' ro_2)) \oplus (NIL \phi ro_2)
\end{aligned}$$

$$(s_1, t_1, b_1, r_1, l_1, tr_1, br_1, tl_1, bl_1, c_1, ro_1) (\Delta_1^{11} \otimes_i) (s_2, t_2, b_2, r_2, l_2, tr_2, br_2, tl_2, bl_2, c_2, ro_2) \\ = (s_0, t_0, b_0, r_0, l_0, tr_0, br_0, tl_0, bl_0, c_0, ro_0)$$

where

$$\begin{aligned} s_0 &= \text{zipwith}_4 f_s s_1 s_2 r_1 l_2 \\ &\quad \text{where } f_s s_1 s_2 r_1 l_2 = (s_1 \phi \text{ gemm } (\_, \phi) r_1 l_2) \oplus (NIL \phi s_2) \\ t_0 &= \text{zipwith}_4 f_t t_1 t_2 tr_1 tl_2 \\ &\quad \text{where } f_t t_1 t_2 tr_1 tl_2 = (t_1 \phi \text{ gemm } (\_, \phi) tr_1 tl_2) \oplus (NIL \phi t_2) \\ b_0 &= \text{zipwith}_4 f_b b_1 b_2 br_1 bl_2 \\ &\quad \text{where } f_b b_1 b_2 br_1 bl_2 = (b_1 \phi \text{ gemm } (\_, \phi) br_1 bl_2) \oplus (NIL \phi b_2) \\ r_0 &= \text{zipwith}_3 f_r r_1 r_2 ro_2 \\ &\quad \text{where } f_r r_1 r_2 ro_2 = \text{map } (\phi ro_2) r_1 \oplus r_2 \\ l_0 &= \text{zipwith}_3 f_l l_1 l_2 ro_1 \\ &\quad \text{where } f_l l_1 l_2 ro_1 = l_1 \phi \text{ map } (ro_1 \phi) l_2 \\ tr_0 &= \text{zipwith } f_{tr} tr_1 tr_2 \\ &\quad \text{where } f_{tr} tr_1 tr_2 = \text{map } (\phi \text{ top}' tr_2) tr_1 \oplus tr_2 \\ br_0 &= \text{zipwith } f_{br} br_1 br_2 \\ &\quad \text{where } f_{br} br_1 br_2 = \text{map } (\phi \text{ top}' br_2) br_1 \oplus br_2 \\ tl_0 &= \text{zipwith } f_{tl} tl_1 tl_2 \\ &\quad \text{where } f_{tl} tl_1 tl_2 = tl_1 \phi \text{ map } (\text{right}' tl_1 \phi) tl_2 \\ bl_0 &= \text{zipwith } f_{bl} bl_1 bl_2 \\ &\quad \text{where } f_{bl} bl_1 bl_2 = bl_1 \phi \text{ map } (\text{right}' bl_1 \phi) bl_2 \\ c_0 &= (c_1 \phi \text{ gemm } (\_, \phi) (\text{right } c_1) (\text{top } c_2)) \oplus (NIL \phi c_2) \\ ro_0 &= \text{zipwith}(\phi) ro_1 ro_2 \end{aligned}$$

### Step 3. Fusing with Almost Homomorphisms

We aim to derive an efficient almost homomorphism for *mrs*. To this end, we give the following theorem showing how to fuse a function with an almost homomorphism to get new another almost homomorphism.

#### Theorem 4.2 (Almost Fusion)

Let  $h$  and  $(\Delta_1^n f_i, \Delta_1^n \oplus_i, \Delta_1^n \otimes_i)$  be given. If there exist  $\odot_i, \ominus_i (i = 1, \dots, n)$  and  $H = h_1 \times h_2 \times \dots \times h_n (h_1 = h)$  such that  $\forall i, \forall x, y$

$$\begin{aligned} h_i (x \oplus_i y) &= H x \odot_i H y \\ h_i (x \otimes_i y) &= H x \ominus_i H y \end{aligned}$$

then

$$h \circ (\pi_1 \circ (\Delta_1^n f_i, \Delta_1^n \oplus_i, \Delta_1^n \otimes_i)) = \pi_1 \circ (\Delta_1^n (h_i \circ f_i), \Delta_1^n \odot_i, \Delta_1^n \ominus_i) . \quad (4)$$

PROOF. The theorem is proven by some calculation and Theorem 2.1.

$$\begin{aligned} &h \circ (\pi_1 \circ (\Delta_1^n f_i, \Delta_1^n \oplus_i, \Delta_1^n \otimes_i)) \\ &= \{ \text{Definition of } H \text{ and } \pi_1 \} \\ &\pi_1 \circ H \circ (\Delta_1^n f_i, \Delta_1^n \oplus_i, \Delta_1^n \otimes_i) \\ &= \{ \text{Theorem 2.1 and the proofs below} \} \\ &\pi_1 \circ (\Delta_1^n (h_i \circ f_i), \Delta_1^n \odot_i, \Delta_1^n \ominus_i) \end{aligned}$$

To complete the above proof, we need to show

$$\begin{cases} H \circ (\Delta_1^n f_i) &= \Delta_1^n (h_i \circ f_i) \\ H(x (\Delta_1^n \oplus_i) y) &= (H x) (\Delta_1^n \odot_i) (H y) \\ H(x (\Delta_1^n \otimes_i) y) &= (H x) (\Delta_1^n \ominus_i) (H y) . \end{cases}$$

These equations are proved as follows.

$$\begin{aligned}
& (H \circ (\Delta_1^n f_i)) a \\
= & \quad \{ \text{Definition of } \Delta \text{ and } H \} \\
& ((h_1 \circ f_1) a, \dots, (h_n \circ f_n) a) \\
= & \quad \{ \text{Definition of } \Delta \} \\
& (\Delta_1^n (h_i \circ f_i)) a
\end{aligned}$$

$$\begin{aligned}
& H (x (\Delta_1^n \oplus_i) y) \\
= & \quad \{ \text{Definition of } \Delta \text{ and } H \} \\
& (h_1 (x \oplus_1 y), \dots, h_n (x \oplus_n y)) \\
= & \quad \{ \text{Assumption of } h_i \} \\
& ((H x) \odot_1 (H y), \dots, (H x) \odot_n (H y)) \\
= & \quad \{ \text{Definition of } \Delta \} \\
& (H x) (\Delta_1^n \odot_i) (H y)
\end{aligned}$$

The third is similar to the second.  $\square$

Theorem 4.2 says that we can fuse a function with an almost homomorphism to get another almost homomorphism by finding  $h_2, \dots, h_n$  together with  $\odot_1, \dots, \odot_n, \oplus_1, \dots, \oplus_n$  that satisfy Eq. (4). Thus, this theorem gives us a systematic way to execute Step 3 of the strategy.

Returning to our example, we apply this theorem to *mrs*. The second function  $p_2$  of our example is `map (map sum)`, so  $h_1 = \text{map (map sum)}$ . Then, we calculate  $h_1 (x \oplus_1 y)$  to find other functions and operators.

$$\begin{aligned}
& h_1 (x \oplus_1 y) \\
= & \quad \{ \text{Expand } x, y \text{ and } h_1 \} \\
& \text{map (map sum)} \\
& \quad ((s_1 \phi \text{ gemm}(\_, \text{zipwith}(\ominus)) b_1 t_2) \ominus (NIL \phi s_2)) \\
= & \quad \{ \text{Definition of map} \} \\
& (\text{map (map sum)} s_1 \phi \\
& \quad \text{map (map sum) (gemm(\_, zipwith}(\ominus)) b_1 t_2)) \\
& \quad \ominus (NIL \phi \text{map (map sum)} s_2)) \\
= & \quad \{ \text{Promotion of map, folding} \} \\
& (h_1 s_1 \phi \text{ gemm}(\_, \text{zipwith}(+)) \\
& \quad (\text{map (map sum)} b_1) (\text{map (map sum)} t_2)) \ominus (NIL \phi h_1 s_2))
\end{aligned}$$

In the last formula, functions applied to  $t_1$  and  $b_1$  should be  $h_2$  and  $h_3$  respectively, which suggests us to define  $h_2, h_3$  and  $\odot_1$  as follows.

$$\begin{aligned}
h_2 = h_3 = & \text{map (map sum)} = h_1 \\
& (s_1, t_1, b_1, r_1, l_1, tr_1, br_1, tl_1, bl_1, c_1, ro_1) \\
& \quad \odot_1 (s_2, t_2, b_2, r_2, l_2, tr_2, br_2, tl_2, bl_2, c_2, ro_2) \\
= & (s_1 \phi \text{ gemm}(\_, \text{zipwith}(+)) b_1 t_2) \ominus (NIL \phi s_2)
\end{aligned}$$

Similarly, we can derive  $\ominus_1$  by calculating  $h_1 (x \otimes_1 y)$  as follows:

$$\begin{aligned}
& (s_1, t_1, b_1, r_1, l_1, tr_1, br_1, tl_1, bl_1, c_1, ro_1) \\
& \quad \otimes_1 (s_2, t_2, b_2, r_2, l_2, tr_2, br_2, tl_2, bl_2, c_2, ro_2) \\
& = \text{zipwith}_4 f_s s_1 s_2 r_1 l_2 \\
& \quad \textbf{where } f_s s_1 s_2 r_1 l_2 = (s_1 \phi \text{ gemm}(\_, +) r_1 l_2) \oplus (NIL \phi s_2)
\end{aligned}$$

and derive other functions and operators by doing similarly about  $\oplus_i$  and  $\otimes_i$ . Finally, we get the following.

$$\text{map}(\text{map } \text{sum}) \circ \text{rects} = \pi_1 \circ ( \Delta_1^{11} f'_i, \Delta_1^{11} \ominus_i, \Delta_1^{11} \ominus_i )$$

**where**

$$\begin{aligned}
\Delta_1^{11} f'_i |a| &= (||a||, ||a||, ||a||, ||a||, ||a||, ||a||, ||a||, ||a||, ||a||, |a|, |a|) \\
(s_1, t_1, b_1, r_1, l_1, tr_1, br_1, tl_1, bl_1, c_1, ro_1) (\Delta_1^{11} \ominus_i) (s_2, t_2, b_2, r_2, l_2, tr_2, br_2, tl_2, bl_2, c_2, ro_2) \\
&= (s_0, t_0, b_0, r_0, l_0, tr_0, br_0, tl_0, bl_0, c_0, ro_0)
\end{aligned}$$

**where**

$$\begin{aligned}
s_0 &= (s_1 \phi \text{ gemm}(\_, \text{zipwith}(+)) b_1 t_2) \oplus (NIL \phi s_2) \\
t_0 &= t_1 \phi \text{ map}(\text{zipwith}(+) c_1) t_2 \\
b_0 &= \text{map}(\lambda z \rightarrow \text{zipwith}(\oplus) z c_2) b_1 \oplus b_2 \\
r_0 &= (r_1 \phi \text{ gemm}(\_, \text{zipwith}(+)) br_1 tr_2) \oplus (NIL \phi r_2) \\
l_0 &= (l_1 \phi \text{ gemm}(\_, \text{zipwith}(+)) bl_1 tl_2) \oplus (NIL \phi l_2) \\
tr_0 &= tr_1 \phi \text{ map}(\text{zipwith}(+) (\text{right}' tr_1)) tr_2 \\
br_0 &= \text{map}(\lambda z \rightarrow \text{zipwith}(+) z (\text{top}' br_2)) br_1 \oplus br_2 \\
tl_0 &= tl_1 \phi \text{ map}(\text{zipwith}(+) (\text{right}' tl_1)) tl_2 \\
bl_0 &= \text{map}(\lambda z \rightarrow \text{zipwith}(+) z (\text{top}' bl_2)) bl_1 \oplus bl_2 \\
c_0 &= \text{zipwith}(+) c_1 c_2 \\
ro_0 &= (ro_1 \phi \text{ gemm}(\_, +) (\text{right } ro_1) (\text{top } ro_2)) \oplus (NIL \phi ro_2) \\
(s_1, t_1, b_1, r_1, l_1, tr_1, br_1, tl_1, bl_1, c_1, ro_1) (\Delta_1^{11} \ominus_i) (s_2, t_2, b_2, r_2, l_2, tr_2, br_2, tl_2, bl_2, c_2, ro_2) \\
&= (s_0, t_0, b_0, r_0, l_0, tr_0, br_0, tl_0, bl_0, c_0, ro_0)
\end{aligned}$$

**where**

$$\begin{aligned}
s_0 &= \text{zipwith}_4 f_s s_1 s_2 r_1 l_2 \\
& \quad \textbf{where } f_s s_1 s_2 r_1 l_2 = (s_1 \phi \text{ gemm}(\_, +) r_1 l_2) \oplus (NIL \phi s_2) \\
t_0 &= \text{zipwith}_4 f_t t_1 t_2 tr_1 tl_2 \\
& \quad \textbf{where } f_t t_1 t_2 tr_1 tl_2 = (t_1 \phi \text{ gemm}(\_, +) tr_1 tl_2) \oplus (NIL \phi t_2) \\
b_0 &= \text{zipwith}_4 f_b b_1 b_2 br_1 bl_2 \\
& \quad \textbf{where } f_b b_1 b_2 br_1 bl_2 = (b_1 \phi \text{ gemm}(\_, +) br_1 bl_2) \oplus (NIL \phi b_2) \\
r_0 &= \text{zipwith}_3 f_r r_1 r_2 ro_2 \\
& \quad \textbf{where } f_r r_1 r_2 ro_2 = \text{map}(\text{+ro}_2) r_1 \oplus r_2 \\
l_0 &= \text{zipwith}_3 f_l l_1 l_2 ro_1 \\
& \quad \textbf{where } f_l l_1 l_2 ro_1 = l_1 \phi \text{ map}(\text{ro}_1+) l_2 \\
tr_0 &= \text{zipwith } f_{tr} tr_1 tr_2 \\
& \quad \textbf{where } f_{tr} tr_1 tr_2 = \text{map}(\text{+top}' tr_2) tr_1 \oplus tr_2 \\
br_0 &= \text{zipwith } f_{br} br_1 br_2 \\
& \quad \textbf{where } f_{br} br_1 br_2 = \text{map}(\text{+top}' br_2) br_1 \oplus br_2 \\
tl_0 &= \text{zipwith } f_{tl} tl_1 tl_2 \\
& \quad \textbf{where } f_{tl} tl_1 tl_2 = tl_1 \phi \text{ map}(\text{right}' tl_1+) tl_2 \\
bl_0 &= \text{zipwith } f_{bl} bl_1 bl_2 \\
& \quad \textbf{where } f_{bl} bl_1 bl_2 = bl_1 \phi \text{ map}(\text{right}' bl_1+) bl_2 \\
c_0 &= (c_1 \phi \text{ gemm}(\_, +) (\text{right } c_1) (\text{top } c_2)) \oplus (NIL \phi c_2) \\
ro_0 &= \text{zipwith}(+) ro_1 ro_2
\end{aligned}$$

In this case, the function  $H$  appeared in Theorem 4.2 is as follows:

$$H = h \times h \times h \times h \times h \times h \times h \times h \times h \times (\text{map sum}) \times (\text{map sum})$$

**where**  $h = \text{map} (\text{map sum})$  .

Some calculation rules used in this derivation are listed in Appendix B.

Then, applying the theorem again with the third function  $p_3 = \text{map max}$ , we obtain another almost-homomorphism with  $H = (\text{map max}) \times id \times id \times id \times id \times id \times id \times id \times id \times id$  as follows:

$$\text{map max} \circ \text{map} (\text{map sum}) \circ \text{rects} = \pi_1 \circ (\Delta_1^{11} f_i'', \Delta_1^{11} \odot'_i, \Delta_1^{11} \ominus'_i)$$

**where**

$$\Delta_1^{11} f_i'' |a| = (|a|, |a|, |a|, |a|, |a|, |a|, |a|, |a|, |a|, |a|, |a|, |a|)$$

$$(s_1, t_1, b_1, r_1, l_1, tr_1, br_1, tl_1, bl_1, c_1, ro_1) (\Delta_1^{11} \odot'_i) (s_2, t_2, b_2, r_2, l_2, tr_2, br_2, tl_2, bl_2, c_2, ro_2)$$

$$= (s_0, t_0, b_0, r_0, l_0, tr_0, br_0, tl_0, bl_0, c_0, ro_0)$$

**where**

$$s_0 = (s_1 \phi \text{map max}(\text{gemm } (\_, \text{zipwith}(+)) b_1 t_2)) \oplus (NIL \phi s_2)$$

$$t_0 = t_1 \phi \text{map} (\text{zipwith}(+) c_1) t_2$$

$$b_0 = \text{map} (\lambda z \rightarrow \text{zipwith}(\oplus) z c_2) b_1 \oplus b_2$$

$$r_0 = (r_1 \phi \text{gemm } (\_, \text{zipwith}(+)) br_1 tr_2) \oplus (NIL \phi r_2)$$

$$l_0 = (l_1 \phi \text{gemm } (\_, \text{zipwith}(+)) bl_1 tl_2) \oplus (NIL \phi l_2)$$

$$tr_0 = tr_1 \phi \text{map} (\text{zipwith}(+) (\text{right}' tr_1)) tr_2$$

$$br_0 = \text{map} (\lambda z \rightarrow \text{zipwith}(+) z (\text{top}' br_2)) br_1 \oplus br_2$$

$$tl_0 = tl_1 \phi \text{map} (\text{zipwith}(+) (\text{right}' tl_1)) tl_2$$

$$bl_0 = \text{map} (\lambda z \rightarrow \text{zipwith}(+) z (\text{top}' bl_2)) bl_1 \oplus bl_2$$

$$c_0 = \text{zipwith}(+) c_1 c_2$$

$$ro_0 = (ro_1 \phi \text{gemm } (\_, +) (\text{right } ro_1) (\text{top } ro_2)) \oplus (NIL \phi ro_2)$$

$$(s_1, t_1, b_1, r_1, l_1, tr_1, br_1, tl_1, bl_1, c_1, ro_1) (\Delta_1^{11} \ominus'_i) (s_2, t_2, b_2, r_2, l_2, tr_2, br_2, tl_2, bl_2, c_2, ro_2)$$

$$= (s_0, t_0, b_0, r_0, l_0, tr_0, br_0, tl_0, bl_0, c_0, ro_0)$$

**where**

$$s_0 = \text{zipwith}_4 f_s s_1 s_2 r_1 l_2$$

**where**  $f_s s_1 s_2 r_1 l_2 = s_1 \uparrow \text{max}(\text{gemm } (\_, +) r_1 l_2) \uparrow s_2$

$$t_0 = \text{zipwith}_4 f_t t_1 t_2 tr_1 tl_2$$

**where**  $f_t t_1 t_2 tr_1 tl_2 = (t_1 \phi \text{gemm } (\_, +) tr_1 tl_2) \oplus (NIL \phi t_2)$

$$b_0 = \text{zipwith}_4 f_b b_1 b_2 br_1 bl_2$$

**where**  $f_b b_1 b_2 br_1 bl_2 = (b_1 \phi \text{gemm } (\_, +) br_1 bl_2) \oplus (NIL \phi b_2)$

$$r_0 = \text{zipwith}_3 f_r r_1 r_2 ro_2$$

**where**  $f_r r_1 r_2 ro_2 = \text{map } (+ro_2) r_1 \oplus r_2$

$$l_0 = \text{zipwith}_3 f_l l_1 l_2 ro_1$$

**where**  $f_l l_1 l_2 ro_1 = l_1 \phi \text{map } (ro_1+) l_2$

$$tr_0 = \text{zipwith } f_{tr} tr_1 tr_2$$

**where**  $f_{tr} tr_1 tr_2 = \text{map } (+\text{top}' tr_2) tr_1 \oplus tr_2$

$$br_0 = \text{zipwith } f_{br} br_1 br_2$$

**where**  $f_{br} br_1 br_2 = \text{map } (+\text{top}' br_2) br_1 \oplus br_2$

$$tl_0 = \text{zipwith } f_{tl} tl_1 tl_2$$

**where**  $f_{tl} tl_1 tl_2 = tl_1 \phi \text{map } (\text{right}' tl_1+) tl_2$

$$bl_0 = \text{zipwith } f_{bl} bl_1 bl_2$$

**where**  $f_{bl} bl_1 bl_2 = bl_1 \phi \text{map } (\text{right}' bl_1+) bl_2$

$$c_0 = (c_1 \phi \text{gemm } (\_, +) (\text{right } c_1) (\text{top } c_2)) \oplus (NIL \phi c_2)$$

$$ro_0 = \text{zipwith}(+) ro_1 ro_2$$

Finally, applying such fusion with *max* will yield the result shown below. This final parallel program uses only  $O(n^3)$  addition operations, which is much better than the initial one. .

$$mrs = \pi_1 \circ (\Delta_1^{11} f_i''', \Delta_1^{11} \odot_i'', \Delta_1^{11} \ominus_i'')$$

where

$$(\Delta_1^{11} f_i''') |a| = (a, |a|, |a|, |a|, |a|, |a|, |a|, |a|, |a|, |a|, |a|)$$

$$(s_1, t_1, b_1, r_1, l_1, tr_1, br_1, tl_1, bl_1, c_1, ro_1) (\Delta_1^{11} \odot_i'') (s_2, t_2, b_2, r_2, l_2, tr_2, br_2, tl_2, bl_2, c_2, ro_2) \\ = (s_0, t_0, b_0, r_0, l_0, tr_0, br_0, tl_0, bl_0, c_0, ro_0)$$

where

$$s_0 = (s_1 \uparrow \max(\text{zipwith}(+) b_1 t_2) \uparrow s_2$$

$$t_0 = \text{zipwith}_3 f_t t_1 c_1 t_2$$

$$\text{where } f_t t_1 c_1 t_2 = t_1 \uparrow (c_1 + t_2)$$

$$b_0 = \text{zipwith}_3 f_b b_1 c_2 b_2$$

$$\text{where } f_b b_1 c_2 b_2 = (b_1 + c_2) \uparrow b_2$$

$$r_0 = (r_1 \phi \text{gemm}(\uparrow, +) (tr br_1) tr_2) \oplus (NIL \phi r_2)$$

$$l_0 = (l_1 \phi \text{gemm}(\uparrow, +) bl_1 (tr tl_2)) \oplus (NIL \phi l_2)$$

$$tr_0 = tr_1 \phi \text{map}_c (\text{zipwith}(+) (right tr_1)) tr_2$$

$$br_0 = \text{map}_c (\text{zipwith}(+) (left br_2)) br_1 \phi br_2$$

$$tl_0 = tl_1 \oplus \text{map}_r (\text{zipwith}(+) (bottom tl_1)) tl_2$$

$$bl_0 = \text{map}_r (\text{zipwith}(+) (top bl_2)) bl_1 \oplus bl_2$$

$$c_0 = \text{zipwith}(+) c_1 c_2$$

$$ro_0 = (ro_1 \phi \text{gemm}(\_, +) (right ro_1) (top ro_2)) \oplus (NIL \phi ro_2)$$

$$(s_1, t_1, b_1, r_1, l_1, tr_1, br_1, tl_1, bl_1, c_1, ro_1) (\Delta_1^{11} \ominus_i'') (s_2, t_2, b_2, r_2, l_2, tr_2, br_2, tl_2, bl_2, c_2, ro_2) \\ = (s_0, t_0, b_0, r_0, l_0, tr_0, br_0, tl_0, bl_0, c_0, ro_0)$$

where

$$s_0 = s_1 \uparrow \max(\text{zipwith}(+) r_1 l_2) \uparrow s_2$$

$$t_0 = (t_1 \phi \text{gemm}(\uparrow, +) tr_1 tl_2) \oplus (NIL \phi t_2)$$

$$b_0 = (b_1 \phi \text{gemm}(\uparrow, +) br_1 bl_2) \oplus (NIL \phi b_2)$$

$$r_0 = \text{zipwith}_3 f_r r_1 r_2 ro_2$$

$$\text{where } f_r r_1 r_2 ro_2 = (r_1 + ro_2) \uparrow r_2$$

$$l_0 = \text{zipwith}_3 f_l l_1 l_2 ro_1$$

$$\text{where } f_l l_1 l_2 ro_1 = l_1 \uparrow (ro_1 + l_2)$$

$$tr_0 = \text{map}_r (\text{zipwith}(+) (top tr_2)) tr_1 \oplus tr_2$$

$$br_0 = \text{map}_r (\text{zipwith}(+) (top br_2)) br_1 \oplus br_2$$

$$tl_0 = tl_1 \phi \text{map}_c (\text{zipwith}(+) (right tl_1)) tl_2$$

$$bl_0 = bl_1 \phi \text{map}_c (\text{zipwith}(+) (right bl_1)) bl_2$$

$$c_0 = (c_1 \phi \text{gemm}(\_, +) (right c_1) (top c_2)) \oplus (NIL \phi c_2)$$

$$ro_0 = \text{zipwith}(+) ro_1 ro_2$$

The function *H* for the final fusion is as follows:

$$H = \max \times (\text{reduce}(\_, \text{zipwith}(\uparrow))) \times (\text{reduce}(\text{zipwith}(\uparrow), \_)) \times (\text{map} (\text{reduce}(\uparrow, \_))) \\ \times (\text{map} (\text{reduce}(\_, \uparrow))) \times (\text{reduce}(\_, \phi)) \times (\text{reduce}(\phi, \_)) \\ \times (\text{reduce}(\_, \oplus)) \times (\text{reduce}(\oplus, \_)) \times id \times id$$

#### Step 4. Optimizing Inner Functions

For our example, we may proceed to optimize the operators and functions such as  $f_i'''$ ,  $\odot_i''$  and  $\ominus_i''$  in the program of Step 3. Since they cannot be made efficient any more, we finish our derivation of efficient parallel program.

## 5. IMPLEMENTATION

In this section, we will give an efficient parallel implementation (on PC clusters) of the parallel skeletons, which are primitive operations on two-dimensional arrays defined in Section 3.1 and Section 3.2. Since a homomorphism can be specified as a composition of the reduce and map skeletons, homomorphisms have efficient parallel implementations. Our parallel skeletons are implemented as a C++ library with MPI. We will report some experimental results, showing programs described in terms of skeletons can be executed efficiently in parallel.

### 5.1 Implementation of Data Parallel Skeletons

The four basic data parallel skeletons of `map`, `zipwith`, `reduce` and `scan` can be efficiently implemented on distributed memory systems. To illustrate this, we separate computations of a skeleton into two parts: local computations within a processor and global computations crossing processors.

For `map` skeleton, we can separate its computation as follows.

$$\begin{aligned}
 \text{map } f &= \text{map } f \circ \text{gather} \circ \text{dist } p q \\
 &= \text{map } f \circ \text{reduce}(\oplus, \phi) \circ \text{dist } p q \\
 &= \text{reduce}(\oplus, \phi) \circ \text{map}(\text{map } f) \circ \text{dist } p q \\
 &= \text{gather} \circ \text{map}(\text{map } f) \circ \text{dist } p q
 \end{aligned}$$

The last formula indicates that we can compute `map f` by distributing a two-dimensional array of the argument to the processors by `dist p q`, applying `map f` to each local array independently on each processor, and finally gathering the results onto the root processor by `gather`. Thus, for a two-dimensional array of  $n \times n$  size we can compute `map f` in  $O(n^2/P)$  parallel time using  $P = pq$  processors and ignoring distribution and collection provided that the function  $f$  can be computed in  $O(1)$  time. This is the same also about `zipwith`.

For `reduce` skeleton, we can separate its computation as follows.

$$\begin{aligned}
 \text{reduce}(\oplus, \otimes) &= \text{reduce}(\oplus, \otimes) \circ \text{gather} \circ \text{dist } p q \\
 &= \text{reduce}(\oplus, \otimes) \circ \text{reduce}(\oplus, \phi) \circ \text{dist } p q \\
 &= \text{reduce}(\oplus, \otimes) \circ \text{map}(\text{reduce}(\oplus, \otimes)) \circ \text{dist } p q
 \end{aligned}$$

The last formula indicates that we can compute `reduce(⊕, ⊗)` by distributing a two-dimensional array of the argument to the processors by `dist p q`, applying `reduce(⊕, ⊗)` to each local array independently on each processor, and finally reducing the results into the root processor by `reduce(⊕, ⊗)` described in the last formula. From the property of Eq. (1), the last reduction over the results of all processors can be computed by using tree-like computation in column and row directions respectively like parallel computation of reduction on one-dimensional lists. Thus, for a two-dimensional array of  $n \times n$  size we can compute `reduce(⊕, ⊗)` in  $O(n^2/P + \log P)$  parallel time using  $P = pq$  processors and ignoring distribution provided that the binary operators  $\oplus$  and  $\otimes$  can be computed in  $O(1)$  time.

For `scan` skeleton, we can separate its computation as follows.

$$\begin{aligned}
 \text{scan}(\oplus, \otimes) &= \text{reduce}(\oplus', \otimes') \circ \text{map}|\cdot| \circ \text{gather} \circ \text{dist } p q \\
 &= \text{reduce}(\oplus', \otimes') \circ \text{map}|\cdot| \circ \text{reduce}(\oplus, \phi) \circ \text{dist } p q \\
 &= \text{reduce}(\oplus', \otimes') \circ \text{map}(\text{reduce}(\oplus', \otimes') \circ \text{map}|\cdot|) \circ \text{dist } p q \\
 &= \text{reduce}(\oplus', \otimes') \circ \text{map}(\text{scan}(\oplus, \otimes)) \circ \text{dist } p q \\
 &= \text{gather} \circ \text{dist } p q \circ \text{reduce}(\oplus', \otimes') \circ \text{map}(\text{scan}(\oplus, \otimes)) \circ \text{dist } p q
 \end{aligned}$$

The second last formula indicates we can compute `scan(⊕, ⊗)` by distributing a two-dimensional array of the argument to the processors by `dist p q`, applying `scan(⊕, ⊗)` to each local array independently on each processor, and finally reducing the results into the root processor by `reduce(⊕', ⊗')`. However, since the result of `scan(⊕, ⊗)` is a two-dimensional array, we want that the last operation of computing `scan(⊕, ⊗)` is `gather` like the case of `map f`. Thus, we compute

underlined  $\text{dist } pq \circ \text{reduce}(\oplus', \otimes')$  instead of the last reduction  $\text{reduce}(\oplus', \otimes')$ . Although under our notation the underlined computation cannot be written in simpler form, we can compute it in sequence in column and row direction like the case of  $\text{reduce}$ . The computation in each direction can be done like those of lists [15]. Or, from the property of Eq. (2), we can compute  $\text{scan}(\oplus, \otimes)$  by computing  $\text{scan}_{\downarrow}(\oplus)$  after  $\text{scan}_{\rightarrow}(\otimes)$ . Note that  $\text{scan}_{\downarrow}(\oplus)$  and  $\text{scan}_{\rightarrow}(\otimes)$  can be computed in the same way of  $\text{scan}$  on list although it performs to two or more lists simultaneously. Thus, for a two-dimensional array of  $n \times n$  size we can compute  $\text{scan}(\oplus, \otimes)$  in  $O(n^2/P + \sqrt{n^2/P} \log P)$  parallel time using  $P = pq$  processors and ignoring distribution and collection provided that the binary operators  $\oplus$  and  $\otimes$  can be computed in  $O(1)$  time.

## 5.2 Implementation of Data Communication Skeletons

We have efficient parallel implementations for the data communication skeletons defined in Section 3.2.

Since  $\text{dist}$  distributes all elements of a two-dimensional array at the root processor to all other processors and  $\text{gather}$  does the inverse, we can compute  $\text{dist}$  and  $\text{gather}$  in  $O(n^2)$  parallel time for a two-dimensional array of  $n \times n$  size.

Although the definition of  $\text{rot}_r f$  given in Section 3 is complicated, the actual operation of  $\text{rot}_r f$  is simple. Function  $\text{rot}_r f$  merely rotates independently  $i$ -th row by  $f i$ , and rotation of each row can be done by four parallel communications. Without losing generality we can assume that the amount of rotation  $r = f i$  satisfies  $0 < r \leq n/2$  where  $n$  is the length of the row because we just reverse the direction of rotation in the case of  $n/2 < r$ . The operations are followings: (1) making groups of  $2r$  processors from the first processor of the row (i.e.  $n/(2r)$  groups are made) and transmitting subarrays of first  $r$  processors to the rest  $r$  processors in each group, (2) considering that processors from the 0th to the  $r$ -th continue behind the last processor, making groups of  $2r$  processors from the  $r$ -th processor of the row and transmitting subarrays of first  $r$  processors to the rest  $r$  processors in each group (i.e. processors in the first  $n/(2r)$  groups have transmitted their subarrays), (3) doing the former two operations on the rest processors which have not transmitted their subarrays yet, considering the processors which have done continue behind the processors. Since more than the half processors have transmitted their subarrays by the end of the former two operations, all processors can transmit their subarrays by the end of third operation. Thus, since the amount of one communication is  $O(n^2/P)$  for  $P$  processors,  $\text{rot}_r f$  can be executed in  $O(n^2/P)$  parallel time. Similarly,  $\text{rot}_c f$  can be executed in  $O(n^2/P)$  parallel time.

## 5.3 Experiments

We implemented the parallel skeletons as a library with C++ and MPI, and did our experiments on a small-scale cluster of four Pentium 4 Xeon 2.0-GHz dualprocessor PCs with 1 GB of memory, connected through a Gigabit Ethernet. The OS was FreeBSD 4.10 and we used gcc 2.95 for the compiler, MPICH 1.1.2 for MPI.

Figures 2 and 3 show speedup of the following parallel skeletons and matrix multiplication described in terms of parallel skeletons with *square*  $x = x^2$  :

- |   |                             |
|---|-----------------------------|
| (1) $\text{map } \textit{square}$ ,                             | (2) $\text{reduce}(+, +)$ , |
| (3) $\text{zipwith}(\lambda xy \rightarrow \sqrt{x^2 + y^2})$ , | (4) $\text{scan}(+, +)$ ,   |
| (5) $\textit{mm}$ (composition of skeletons, see Section 3.3) . |                             |

The inputs for the first five parallel programs are  $8000 \times 8000$  matrices, and  $1800 \times 1800$  matrices for  $\textit{mm}$ . The computation times of the above programs on one processor are 4.72sec, 0.32sec, 4.85sec, 0.36sec and 135.3sec respectively.

The result shows programs described in terms of skeletons can be executed efficiently in parallel, and proves the success of our framework. The speedup of matrix multiplication is super-linear. This can happen in large matrix operations where the matrix on a single processor



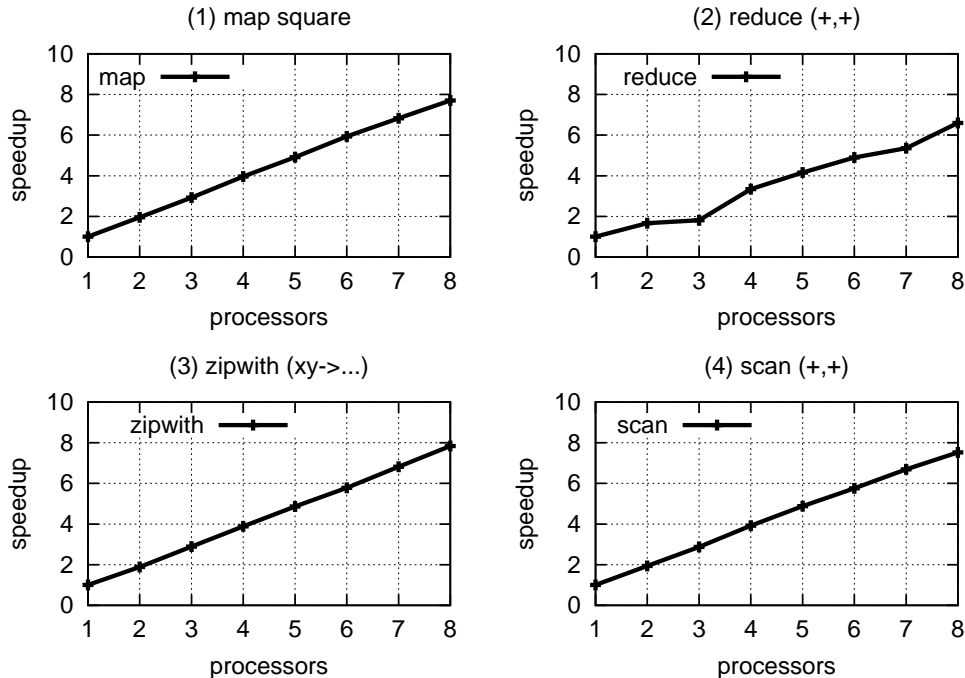


Figure 2: Speedup of Parallel Skeletons

is large with respect to the cache size. It is reasonable that super-linear speedup is achieved here.

Finally, we list part of the C++ code of *mm* written with the skeleton library in Figure 4, to give a concrete impression of the conciseness our library provides.

## 6. RELATED WORKS

Besides the related work as in the introduction, our work is closely related the active researches on matrix representation for parallel computations and the compositional approach to parallel program development.

### Recursive Matrix Representations

Wise et al. [33] propose representation of a two-dimensional array by a quadtree, i.e. a two-dimensional array recursively constructed by four small sub-arrays of the same size. This representation is suitable for describing recursive blocked algorithms [11], which can provide better performance than existing algorithms for some matrix computations such as LU and QR factorizations [12, 34]. However, the quadtree representation requires the size of two-dimensional arrays to be the power of 2. Moreover, once a two-dimensional array is represented by a quadtree, we cannot reblock the array by restructuring the quadtree, which would prevent us from developing more parallelism in the recursive blocked algorithms on them.

A more natural representation of a two-dimensional array is to use nested one-dimensional arrays (lists) [4, 30, 22]. The advantage is that many results developed for lists can be reused. However, this representation imposes much restriction on the access order of elements.

The abide tree representation, as used in this paper, was first proposed by Bird [4], as an extension of one-dimensional join list. However, the focus there is on derivation of sequential programs for manipulating two-dimensional arrays, and there is little study on the framework for developing efficient parallel programs. Our work provides a good complement.

### Compositional Parallel Programming

This work were greatly inspired by the success of compositional (skeletal) parallel programming on one-dimensional arrays (lists) [27], and our initial motivation was to import the results so

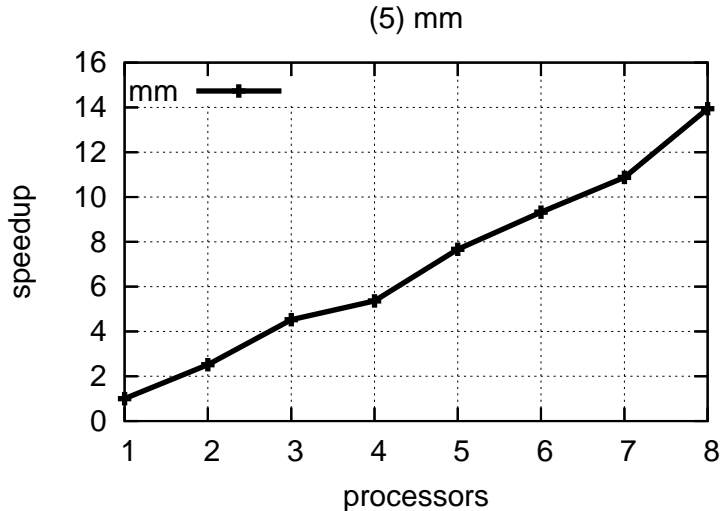


Figure 3: Speedup of Matrix Multiplication

---

```

template <class C, class A, class B>
void mm(dist_matrix<C> &Z2, const dist_matrix<A> &X2, const dist_matrix<B> &Y2)
{
    dist_matrix < matrix < int > > *A2;
    dist_matrix < matrix < int > > *B2;
    A2 = all_rows2(X2);
    B2 = all_cols2(Y2);
    m_skeletons::map_i(Tri< matrix <B> >(), *B2);
    m_skeletons::zipwith(Iprod<C>(), *A2, *B2, Z2);
    delete B2;
    delete A2;
}

```

---

Figure 4: C++ Code of *mm*

far to two-dimensional arrays. This turns out to be more difficult than we had expected.

Compositional parallel Programming using Bird-Meertens Formalism (BMF) has been attracting many researchers. The initial BMF [3] was designed as a calculus for deriving (sequential) efficient programs on lists. Skillicorn [29] showed that BMF could also provide an architecture independent parallel model for parallel programming because a small fixed set of higher order functions (skeletons) in BMF such as map and reduce can be mapped efficiently to a wide range of parallel architectures.

Systematic programming methods have actively been studied in the framework of skeletal (compositional) parallel programming on lists. The diffusion theorem [21] gives a powerful method to obtain suitable composition of skeletons for a program recursively defined on lists and trees. Chin et al. [20, 6] have studied a systematic method to derive an associative operator which plays an important role in parallelization, based on which Xu et al. [35] build an automatic derivation system for parallelizing recursive linear functions with normalization rules.

## 7. CONCLUSION

In this paper, we propose a compositional framework which allows users, even with little knowledge about parallel machines, to easily describe safe and efficient parallel computation over two-dimensional arrays. In our framework, two-dimensional arrays are represented by the abide-tree which supports systematic development of parallel programs and architecture independent implementation, and programmers can easily build up a complicated parallel system by defining

basic components recursively, putting components compositionally, and improving efficiency systematically. The power of our approach is seen from the nontrivial programming examples of matrix multiplication and QR decomposition, and a successful derivation of an involved efficient parallel programs for the maximum rectangle sum problem [18]. A demonstration of an efficient implementation of basic computation skeletons (in C++ and MPI) on distributed PC clusters guarantees that programs composed by these parallel skeletons can be efficiently executed.

This work is still in an early stage, and there are at least two things to do. One is to construct more powerful theories for a systematic programming methodology, in which we can develop efficient and correct parallel programs by parallel skeletons from their recursive specifications. Another is to study an automatic optimization mechanism, which can eliminate inefficiency due to compositional or nested uses of parallel skeletons in parallel programs. It is also our future work to compare our matrix computation algorithms with existing routines (e.g. BLAS).

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## A. EXAMPLES OF *rects* AND SO ON.

We give example values of eleven functions which constructs the mutually defined function *rects*.

$$\mathit{segs} \begin{pmatrix} a & b \\ c & d \end{pmatrix} = \left( \begin{pmatrix} (a) & (a \ b) \\ & (b) \end{pmatrix} \begin{pmatrix} \begin{pmatrix} (a) & (a \ b) \\ (c) & (c \ d) \end{pmatrix} \\ \begin{pmatrix} (b) \\ (d) \end{pmatrix} \end{pmatrix} \right),$$

$$\mathit{tops} \begin{pmatrix} a & b \\ c & d \end{pmatrix} = \left( \begin{pmatrix} (a) & (a \ b) \\ & (b) \end{pmatrix} \begin{pmatrix} \begin{pmatrix} (a) & (a \ b) \\ (c) & (c \ d) \end{pmatrix} \\ \begin{pmatrix} (b) \\ (d) \end{pmatrix} \end{pmatrix} \right), \quad \mathit{bottoms} \begin{pmatrix} a & b \\ c & d \end{pmatrix} = \left( \begin{pmatrix} \begin{pmatrix} (a) & (a \ b) \\ (c) & (c \ d) \end{pmatrix} \\ \begin{pmatrix} (b) \\ (d) \end{pmatrix} \end{pmatrix} \right),$$

$$\mathit{rights} \begin{pmatrix} a & b \\ c & d \end{pmatrix} = \left( \begin{pmatrix} (a \ b) \\ (b) \end{pmatrix} \begin{pmatrix} \begin{pmatrix} (a \ b) \\ (c \ d) \end{pmatrix} \\ \begin{pmatrix} (d) \\ (c \ d) \end{pmatrix} \end{pmatrix} \right), \quad \mathit{lefts} \begin{pmatrix} a & b \\ c & d \end{pmatrix} = \left( \begin{pmatrix} (a) & (a \ b) \\ (c) & (c \ d) \end{pmatrix} \begin{pmatrix} \begin{pmatrix} (a) & (a \ b) \\ (c) & (c \ d) \end{pmatrix} \\ \begin{pmatrix} (d) \\ (c \ d) \end{pmatrix} \end{pmatrix} \right),$$

$$\mathit{toprights} \begin{pmatrix} a & b \\ c & d \end{pmatrix} = \left( \begin{pmatrix} (a \ b) \\ (b) \end{pmatrix} \begin{pmatrix} \begin{pmatrix} (a \ b) \\ (c \ d) \end{pmatrix} \\ \begin{pmatrix} (d) \\ (c \ d) \end{pmatrix} \end{pmatrix} \right), \quad \mathit{bottomrights} \begin{pmatrix} a & b \\ c & d \end{pmatrix} = \left( \begin{pmatrix} \begin{pmatrix} (a \ b) \\ (c \ d) \end{pmatrix} \\ \begin{pmatrix} (b) \\ (d) \end{pmatrix} \end{pmatrix} \right),$$

$$\mathit{toplefts} \begin{pmatrix} a & b \\ c & d \end{pmatrix} = \left( \begin{pmatrix} (a) & (a \ b) \\ (c) & (c \ d) \end{pmatrix} \begin{pmatrix} \begin{pmatrix} (a) & (a \ b) \\ (c) & (c \ d) \end{pmatrix} \\ \begin{pmatrix} (d) \\ (c \ d) \end{pmatrix} \end{pmatrix} \right), \quad \mathit{bottomlefts} \begin{pmatrix} a & b \\ c & d \end{pmatrix} = \left( \begin{pmatrix} \begin{pmatrix} (a) & (a \ b) \\ (c) & (c \ d) \end{pmatrix} \\ \begin{pmatrix} (d) \\ (c \ d) \end{pmatrix} \end{pmatrix} \right),$$

$$\text{cols} \begin{pmatrix} a & b \\ c & d \end{pmatrix} = \begin{pmatrix} \begin{pmatrix} a \\ c \end{pmatrix} & \begin{pmatrix} a & b \\ c & d \end{pmatrix} \\ & \begin{pmatrix} b \\ d \end{pmatrix} \end{pmatrix}, \text{rows} \begin{pmatrix} a & b \\ c & d \end{pmatrix} = \begin{pmatrix} (a \ b) & \begin{pmatrix} a & b \\ c & d \end{pmatrix} \\ & \begin{pmatrix} c & d \\ c & d \end{pmatrix} \end{pmatrix}.$$

## B. SOME CALCULATION RULES

We summarize the calculation rules used in Section 4 for derivation of the efficient parallel program for solving the maximum rectangle sum problems.

### B.1 Rule I

$$\begin{aligned} \text{map } f (\text{zipwith}(\oplus) x y) &= \text{zipwith}(\oplus') (\text{map } f x) (\text{map } f y) \\ &\Leftarrow \forall a, b \ f (a \oplus b) = f a \oplus' f b \end{aligned}$$

Proof. The induction on the structure of abide trees.

$$\begin{aligned} &\text{map } f (\text{zipwith}(\oplus) |a| |b|) \\ &= \{ \text{def. of zipwith, map} \} \\ &\quad |f (a \oplus b)| \\ &= \{ \text{hypo.} \} \\ &\quad |f a \oplus' f b| \\ &= \{ \text{def. of zipwith, map} \} \\ &\quad \text{zipwith}(\oplus') (\text{map } f |a|) (\text{map } f |b|) \end{aligned}$$

$$\begin{aligned} &\text{map } f (\text{zipwith}(\oplus) (x \ominus y) (u \ominus v)) \\ &= \{ \text{def. of zipwith, map} \} \\ &\quad \text{map } f (\text{zipwith}(\oplus) x u) \ominus \text{map } f (\text{zipwith}(\oplus) y v) \\ &= \{ \text{hypo. of induction} \} \\ &\quad \text{zipwith}(\oplus') (\text{map } f x) (\text{map } f u) \ominus \text{zipwith}(\oplus') (\text{map } f y) (\text{map } f v) \\ &= \{ \text{def. of zipwith, map} \} \\ &\quad \text{zipwith}(\oplus') (\text{map } f (x \ominus y)) (\text{map } f (u \ominus v)) \end{aligned}$$

$$\begin{aligned} &\text{map } f (\text{zipwith}(\oplus) (x \phi y) (u \phi v)) \\ &= \{ \text{similar to } \ominus \} \\ &\quad \text{zipwith}(\oplus') (\text{map } f (x \phi y)) (\text{map } f (u \phi v)) \end{aligned}$$

### B.2 Rule II

$$\text{map} (\text{reduce}(\oplus, \otimes)) (\text{zipwith}(\oplus) x y) = \text{zipwith}(\oplus) (\text{map} (\text{reduce}(\oplus, \otimes)) x) (\text{map} (\text{reduce}(\oplus, \otimes)) y)$$

Proof. Rule I and the following calculation with  $f = \text{reduce}(\oplus, \otimes)$ ,  $\oplus = \ominus$ ,  $\oplus' = \oplus$ .

$$\text{reduce}(\oplus, \otimes) (a \oplus b) = \text{reduce}(\otimes, \oplus) a \oplus \text{reduce}(\otimes, \oplus) b$$

### B.3 Rule III

$$\begin{aligned} \text{map } f (\text{gemm}(\oplus, \otimes) x y) &= \text{gemm}(\oplus', \otimes') (\text{map } f x) (\text{map } f y) \\ &\Leftarrow \forall a, b \quad f (a \oplus b) = f a \oplus' f b, \quad f (a \otimes b) = f a \otimes' f b \end{aligned}$$

Proof. The induction on the structure of abide trees.

$$\begin{aligned} &\text{map } f (\text{gemm}(\oplus, \otimes) |a| |b|) \\ &= \quad \{ \text{def. of } \text{gemm}, \text{map} \} \\ &\quad |f (a \otimes b)| \\ &= \quad \{ \text{hypo.} \} \\ &\quad |f a \otimes' f b| \\ &= \quad \{ \text{def. of } \text{gemm}, \text{map} \} \\ &\quad \text{gemm}(\oplus', \otimes') (\text{map } f |a|) (\text{map } f |b|) \end{aligned}$$

$$\begin{aligned} &\text{map } f (\text{gemm}(\oplus, \otimes) (x \oplus y) z) \\ &= \quad \{ \text{def. of } \text{gemm}, \text{map} \} \\ &\quad \text{map } f (\text{gemm}(\oplus, \otimes) x z) \oplus \text{map } f (\text{gemm}(\oplus, \otimes) y z) \\ &= \quad \{ \text{hypo. of induction} \} \\ &\quad \text{gemm}(\oplus', \otimes') (\text{map } f x) (\text{map } f z) \oplus \text{gemm}(\oplus', \otimes') (\text{map } f y) (\text{map } f z) \\ &= \quad \{ \text{def. of } \text{gemm}, \text{map} \} \\ &\quad \text{gemm}(\oplus', \otimes') (\text{map } f (x \oplus y)) (\text{map } f z) \end{aligned}$$

$$\begin{aligned} &\text{map } f (\text{gemm}(\oplus, \otimes) x (y \oplus z)) \\ &= \quad \{ \text{similar to above} \} \\ &\quad \text{gemm}(\oplus', \otimes') (\text{map } f x) (\text{map } f (y \oplus z)) \end{aligned}$$

$$\begin{aligned} &\text{map } f (\text{gemm}(\oplus, \otimes) (x \oplus y) (u \oplus v)) \\ &= \quad \{ \text{def. of } \text{gemm}, \text{map} \} \\ &\quad \text{map } f (\text{zipwith}(\oplus) (\text{gemm}(\oplus, \otimes) x u) (\text{gemm}(\oplus, \otimes) y v)) \\ &= \quad \{ \text{I} \} \\ &\quad \text{zipwith}(\oplus') (\text{map } f (\text{gemm}(\oplus, \otimes) x u)) (\text{map } f (\text{gemm}(\oplus, \otimes) y v)) \\ &= \quad \{ \text{hypo. of induction} \} \\ &\quad \text{zipwith}(\oplus') (\text{gemm}(\oplus', \otimes') (\text{map } f x) (\text{map } f u)) (\text{gemm}(\oplus', \otimes') (\text{map } f y) (\text{map } f v)) \\ &= \quad \{ \text{def. of } \text{gemm}, \text{map} \} \\ &\quad \text{gemm}(\oplus', \otimes') (\text{map } f (x \oplus y)) (\text{map } f z) \end{aligned}$$

## B.4 Rule IV

$$\begin{aligned} \text{map } f (\text{map}(\oplus x) y) &= \text{map } (\otimes'(f x))(\text{map } f y) \\ &\Leftarrow \forall a, b \quad f (a \oplus b) = f a \oplus' f b \end{aligned}$$

Proof. The induction on the structure of abide trees.

$$\begin{aligned} &\text{map } f (\text{map}(\oplus x) |a|) \\ &= \quad \{ \text{def. of map } \} \\ &\quad |f (x \oplus a)| \\ &= \quad \{ \text{hypo. } \} \\ &\quad |f x \oplus' f a| \\ &= \quad \{ \text{def. of map } \} \\ &\quad \text{map } (\otimes'(f x))(\text{map } f y) \end{aligned}$$

$$\begin{aligned} &\text{map } f (\text{map}(\oplus x) (y \phi z)) \\ &= \quad \{ \text{def. of map } \} \\ &\quad \text{map } f (\text{map}(\oplus x) y) \phi \text{map } f (\text{map}(\oplus x) z) \\ &= \quad \{ \text{hypo. of induction } \} \\ &\quad \text{map } (\otimes'(f x))(\text{map } f y) \phi \text{map } (\otimes'(f x))(\text{map } f z) \\ &= \quad \{ \text{def. of map } \} \\ &\quad \text{map } (\otimes'(f x))(\text{map } f (y \phi z)) \end{aligned}$$

The incuntion case for  $\ominus$  is proved similarly.

The following is an instance of this rule:

$$\text{map } \text{sum } (\text{zipwith } (\ominus) a b) = \text{zipwith } (+) (\text{map } \text{sum } a) (\text{map } \text{sum } b)$$

## B.5 Rule V

$$\text{map } f (\text{right}' x) = \text{right}'(\text{map } (\text{map } f) x)$$

Proof.

$$\begin{aligned} &\text{map } f \circ \text{right}' \\ &= \quad \{ \text{def. of } \text{right}' \} \\ &\quad \text{map } f \circ \text{the } \circ \text{right} \\ &= \quad \{ \text{def. of } \text{right} \} \\ &\quad \text{map } f \circ \text{the } \circ \text{reduce}(\ominus, \gg) \circ \text{map } |\cdot| \\ &= \quad \{ \text{def. of the, map } \} \\ &\quad \text{the } \circ \text{map } (\text{map } f) \circ \text{reduce}(\ominus, \gg) \circ \text{map } |\cdot| \\ &= \quad \{ \text{VI } \} \\ &\quad \text{the } \circ \text{reduce}(\ominus, \gg) \circ \text{map } (\text{map } (\text{map } f)) \text{map } |\cdot| \\ &= \quad \{ \text{def. of } |\cdot|, \text{map } \} \\ &\quad \text{the } \circ \text{reduce}(\ominus, \gg) \circ \text{map } |\cdot| \circ \text{map } (\text{map } f) \\ &= \quad \{ \text{def. of } \text{right}' \} \\ &\quad \text{right}' \circ \text{map } (\text{map } f) \end{aligned}$$



This rule for  $top'$  holds similarly.

### B.6 Rule VI

$$\begin{aligned} \text{map } f \circ \text{reduce}(\oplus, \otimes) &= \text{reduce}(\oplus, \otimes) \circ \text{map} (\text{map } f) \\ &\Leftarrow \oplus, \otimes \in \{\oplus, \phi, \ll, \gg\} \end{aligned}$$

Proof.

$$\begin{aligned} &\text{map } f (\text{reduce}(\oplus, \otimes) |a|) \\ &= \{ \text{def. of reduce} \} \\ &\quad \text{map } f a \\ &= \{ \text{def. of reduce} \} \\ &\quad \text{reduce}(\oplus, \otimes) | \text{map } f a | \\ &= \{ \text{def. of map} \} \\ &\quad \text{reduce}(\oplus, \otimes) (\text{map} (\text{map } f) |a|) \end{aligned}$$

$$\begin{aligned} &\text{map } f (\text{reduce}(\oplus, \otimes) (x \phi y)) \\ &= \{ \text{def. of reduce} \} \\ &\quad \text{map } f (\text{reduce}(\oplus, \otimes) x \otimes \text{reduce}(\oplus, \otimes)y) \\ &= \{ \text{below} \} \\ &\quad \text{map } f (\text{reduce}(\oplus, \otimes) x) \otimes \text{map } f (\text{reduce}(\oplus, \otimes)y) \\ &= \{ \text{hypo. of induction} \} \\ &\quad \text{reduce}(\oplus, \otimes) (\text{map} (\text{map } f) x) \otimes \text{reduce}(\oplus, \otimes) (\text{map} (\text{map } f) y) \\ &= \{ \text{def. of map, reduce} \} \\ &\quad \text{reduce}(\oplus, \otimes) (\text{map} (\text{map } f) (x \phi y)) \end{aligned}$$

The incuntion case for  $\oplus$  is proved similarly.

$$\text{map } f (x \oplus y) = \text{map } f x \oplus \text{map } f y \Leftarrow \oplus \in \{\oplus, \phi, \ll, \gg\}$$

Proof.

$$\begin{aligned} \text{map } f (x \phi y) &= \text{map } f x \phi \text{map } f y \\ \text{map } f (x \oplus y) &= \text{map } f x \oplus \text{map } f y \\ \text{map } f (x \gg y) &= \text{map } f y = \text{map } f x \gg \text{map } f y \\ \text{map } f (x \ll y) &= \text{map } f x = \text{map } f x \ll \text{map } f y \end{aligned}$$

### B.7 Rule VII

$$\begin{aligned} \text{map } f (\text{zipwith}_4 g x u w a) &= \text{zipwith}_4 g' (\text{map } f_1 x) (\text{map } f_2 u) (\text{map } f_3 w) (\text{map } f_4 a) \\ &\Leftarrow f (g x u w a) = g' (f_1 x) (f_2 u) (f_3 w) (f_4 a) \end{aligned}$$

Proof. The induction on the structure of abide trees.

$$\begin{aligned}
& \text{map } f (\text{zipwith}_4 g |a| |b| |c| |d|) \\
= & \quad \{ \text{def. of zipwith, map} \} \\
& |f (g a b c d)| \\
= & \quad \{ \text{hypo.} \} \\
& |g' (f_1 a) (f_2 b) (f_3 c) (f_4 d)| \\
= & \quad \{ \text{def. of zipwith, map} \} \\
& \text{zipwith}_4 g' (\text{map } f_1 |a|) (\text{map } f_2 |b|) (\text{map } f_3 |c|) (\text{map } f_4 |d|)
\end{aligned}$$

$$\begin{aligned}
& \text{map } f (\text{zipwith}_4 g (a \phi x) (b \phi y) (c \phi z) (d \phi w)) \\
= & \quad \{ \text{def. of zipwith, map} \} \\
& \text{map } f (\text{zipwith}_4 g a b c d) \phi \text{map } f (\text{zipwith}_4 g x y z w) \\
= & \quad \{ \text{hypo. of induction} \} \\
& \text{zipwith}_4 g' (\text{map } f_1 a) (\text{map } f_2 b) (\text{map } f_3 c) (\text{map } f_4 d) \\
& \phi \text{zipwith}_4 g' (\text{map } f_1 x) (\text{map } f_2 y) (\text{map } f_3 z) (\text{map } f_4 w) \\
= & \quad \{ \text{def. of zipwith, map} \} \\
& \text{zipwith}_4 g' (\text{map } f_1 (a \phi x)) (\text{map } f_2 (b \phi y)) (\text{map } f_3 (c \phi z)) (\text{map } f_4 (d \phi w))
\end{aligned}$$

The incuntion case for  $\ominus$  is proved similarly.

## B.8 Rule VIII

$$\text{sum} \circ (\phi x) = (+(\text{sum } x)) \circ \text{sum}$$

Proof.

$$(\text{sum} \circ (\phi x)) y = \text{sum } (y \phi x) = \text{sum } y + \text{sum } x = ((+(\text{sum } x)) \circ \text{sum}) y$$

## B.9 Rule IX

$$\begin{aligned}
& \text{map } \text{sum}(\text{map } (\phi \text{top}' tr_2) tr_1 \ominus tr_2) \\
= & \quad \{ \text{def. of map} \} \\
& \text{map } \text{sum}(\text{map } (\phi \text{top}' tr_2) tr_1) \ominus \text{map } \text{sum} tr_2 \\
= & \quad \{ \text{def. of map} \} \\
& \text{map } (\text{sum} \circ (\phi \text{top}' tr_2)) tr_1 \ominus \text{map } \text{sum} tr_2 \\
= & \quad \{ \text{V, VIII} \} \\
& \text{map } (+ \text{top}' (\text{map } \text{sum } tr_2)) (\text{map } \text{sum } tr_1) \ominus \text{map } \text{sum} tr_2
\end{aligned}$$

## B.10 Rule X

$$\begin{aligned}
& \text{reduce}(\oplus, \oplus)(\text{zipwith}(\otimes) (\text{zipwith}(\oplus) a b) (\text{zipwith}(\oplus) c d)) \\
= & \text{reduce}(\oplus, \oplus)(\text{zipwith}(\otimes) a c) \oplus \text{reduce}(\oplus, \oplus)(\text{zipwith}(\otimes) a d) \\
& \oplus \text{reduce}(\oplus, \oplus)(\text{zipwith}(\otimes) b c) \oplus \text{reduce}(\oplus, \oplus)(\text{zipwith}(\otimes) b d) \\
\Leftarrow & (a \oplus b) \otimes (c \oplus d) = (a \otimes c) \oplus (a \otimes d) \oplus (b \otimes c) \oplus (b \otimes d)
\end{aligned}$$

Proof. The induction on the structure of abide trees.

$$\begin{aligned}
& \text{reduce}(\oplus, \oplus)(\text{zipwith}(\otimes) (\text{zipwith}(\oplus) |a| |b|)) (\text{zipwith}(\otimes) (\text{zipwith}(\oplus) |c| |d|)) \\
= & \quad \{ \text{def. of zipwith, reduce} \} \\
& (a \oplus b) \otimes (c \oplus d) \\
= & \quad \{ \text{hypo.} \} \\
& (a \otimes c) \oplus (a \otimes d) \oplus (b \otimes c) \oplus (b \otimes d) \\
= & \quad \{ \text{def. of zipwith, reduce} \} \\
& \text{reduce}(\oplus, \oplus)(\text{zipwith}(\otimes) |a| |c|) \oplus \text{reduce}(\oplus, \oplus)(\text{zipwith}(\otimes) |a| |d|) \\
& \oplus \text{reduce}(\oplus, \oplus)(\text{zipwith}(\otimes) |b| |c|) \oplus \text{reduce}(\oplus, \oplus)(\text{zipwith}(\otimes) |b| |d|)
\end{aligned}$$

$$\begin{aligned}
& \text{reduce}(\oplus, \oplus)(\text{zipwith}(\otimes) (\text{zipwith}(\oplus) (a_1 \oplus a_2) (b_1 \oplus b_2))) (\text{zipwith}(\otimes) (\text{zipwith}(\oplus) (c_1 \oplus c_2) (d_1 \oplus d_2))) \\
= & \quad \{ \text{def. of zipwith, reduce} \} \\
& \text{reduce}(\oplus, \oplus)(\text{zipwith}(\otimes) (\text{zipwith}(\oplus) a_1 b_1)) (\text{zipwith}(\otimes) (\text{zipwith}(\oplus) c_1 d_1)) \\
& \oplus \text{reduce}(\oplus, \oplus)(\text{zipwith}(\otimes) (\text{zipwith}(\oplus) a_2 b_2)) (\text{zipwith}(\otimes) (\text{zipwith}(\oplus) c_2 d_2)) \\
= & \quad \{ \text{hypo. of induction} \} \\
& \text{reduce}(\oplus, \oplus)(\text{zipwith}(\otimes) a_1 c_1) \oplus \text{reduce}(\oplus, \oplus)(\text{zipwith}(\otimes) a_1 d_1) \\
& \oplus \text{reduce}(\oplus, \oplus)(\text{zipwith}(\otimes) b_1 c_1) \oplus \text{reduce}(\oplus, \oplus)(\text{zipwith}(\otimes) b_1 d_1) \\
& \oplus \text{reduce}(\oplus, \oplus)(\text{zipwith}(\otimes) a_2 c_2) \oplus \text{reduce}(\oplus, \oplus)(\text{zipwith}(\otimes) a_2 d_2) \\
& \oplus \text{reduce}(\oplus, \oplus)(\text{zipwith}(\otimes) b_2 c_2) \oplus \text{reduce}(\oplus, \oplus)(\text{zipwith}(\otimes) b_2 d_2) \\
= & \quad \{ \text{def. of zipwith, reduce} \} \\
& \text{reduce}(\oplus, \oplus)(\text{zipwith}(\otimes) (a_1 \oplus a_2) (c_1 \oplus c_2)) \oplus \text{reduce}(\oplus, \oplus)(\text{zipwith}(\otimes) (a_1 \oplus a_2) (d_1 \oplus d_2)) \\
& \oplus \text{reduce}(\oplus, \oplus)(\text{zipwith}(\otimes) (b_1 \oplus b_2) (c_1 \oplus c_2)) \oplus \text{reduce}(\oplus, \oplus)(\text{zipwith}(\otimes) (b_1 \oplus b_2) (d_1 \oplus d_2))
\end{aligned}$$

The incuntion case for  $\ominus$  is proved similarly.

## B.11 Rule XI

$$\begin{aligned}
& \text{max} (\text{map } \text{max} (\text{gemm}(\_, \text{zipwith}(+)) b t)) \\
= & \quad \text{max} (\text{zipwith}(+) (\text{reduce} (\text{zipwith}(\uparrow), \_) b) (\text{reduce} (\_, \text{zipwith}(\uparrow)) t)) \\
& \quad \Leftarrow \text{width } b = 1, \text{height } t = 1
\end{aligned}$$

Proof. The induction on the structure of abide trees.

$$\begin{aligned}
& \text{max} (\text{map } \text{max} (\text{gemm}(\_, \text{zipwith}(+)) |b| |t|)) \\
= & \quad \{ \text{def. of gemm} \} \\
& \text{max} (\text{map } \text{max} (|\text{zipwith}(+) b t|)) \\
= & \quad \{ \text{def. of zipwith, map, max} \} \\
& \text{max} (\text{zipwith}(+) b t) \\
= & \quad \{ \text{def. of reduce} \} \\
& \text{max} (\text{zipwith}(+) (\text{reduce} (\text{zipwith}(\uparrow), \_) |b|) (\text{reduce} (\_, \text{zipwith}(\uparrow)) |t|))
\end{aligned}$$

$$\begin{aligned}
& \max(\text{map } \max(\text{gemm}(\_, \text{zipwith}(+)) (b_1 \oplus b_2) (t_1 \phi t_2))) \\
= & \quad \{ \text{def. of } \text{gemm} \} \\
& \max(\text{map } \max(((\text{gemm}(\_, \text{zipwith}(+)) b_1 t_1) \phi (\text{gemm}(\_, \text{zipwith}(+)) b_1 t_2)) \\
& \quad \oplus ((\text{gemm}(\_, \text{zipwith}(+)) b_2 t_1) \phi (\text{gemm}(\_, \text{zipwith}(+)) b_2 t_2)))) \\
= & \quad \{ \text{def. of } \max \} \\
& \max(\text{map } \max(\text{gemm}(\_, \text{zipwith}(+)) b_1 t_1)) \uparrow \\
& \quad \max(\text{map } \max(\text{gemm}(\_, \text{zipwith}(+)) b_1 t_2)) \\
& \quad \uparrow \max(\text{map } \max(\text{gemm}(\_, \text{zipwith}(+)) b_2 t_1)) \\
& \quad \uparrow \max(\text{map } \max(\text{gemm}(\_, \text{zipwith}(+)) b_2 t_2)) \\
= & \quad \{ \text{hypo. of induction} \} \\
& \max(\text{zipwith}(+) (\text{reduce}(\text{zipwith}(\uparrow), \_) b_1) (\text{reduce}(\_, \text{zipwith}(\uparrow)) t_1)) \\
& \quad \uparrow \max(\text{zipwith}(+) (\text{reduce}(\text{zipwith}(\uparrow), \_) b_1) (\text{reduce}(\_, \text{zipwith}(\uparrow)) t_2)) \\
& \quad \quad \uparrow \max(\text{zipwith}(+) (\text{reduce}(\text{zipwith}(\uparrow), \_) b_2) (\text{reduce}(\_, \text{zipwith}(\uparrow)) t_1)) \\
& \quad \quad \quad \uparrow \max(\text{zipwith}(+) (\text{reduce}(\text{zipwith}(\uparrow), \_) b_2) (\text{reduce}(\_, \text{zipwith}(\uparrow)) t_2)) \\
= & \quad \{ X \text{ with } \oplus = \uparrow, \otimes = + \} \\
& \max(\text{zipwith}(+) (\text{reduce}(\text{zipwith}(\uparrow), \_) (b_1 \oplus b_2)) (\text{reduce}(\_, \text{zipwith}(\uparrow)) (t_1 \phi t_2)))
\end{aligned}$$

## B.12 Rule XII

$$\begin{aligned}
& \max(\text{zipwith}_4 f_s s_1 s_2 r_1 l_2) \\
= & \max s_1 \uparrow \max s_2 \uparrow \max(\text{zipwith}(+) (\text{map } \text{reduce}(\uparrow, \_) r_1) (\text{map } \text{reduce}(\_, \uparrow) l_2)) \\
& \quad \mathbf{where} \ f_s s_1 s_2 r_1 l_2 = s_1 \uparrow \max(\text{gemm}(\_, +) r_1 l_2) \uparrow s_2 \\
& \quad \Leftarrow \text{width of elements of } r_1 = 1, \text{height of elements of } l_2 = 1
\end{aligned}$$

Proof. First, we prove the following equation by the induction on the structure of abide trees.

$$\begin{aligned}
& \max(\text{zipwith}_4 f_s s_1 s_2 r_1 l_2) = \max s_1 \uparrow \max s_2 \uparrow \max(\text{zipwith } f'_s r_1 l_2) \\
& \quad \mathbf{where} \ f'_s r_1 l_2 = \max(\text{gemm}(\_, +) r_1 l_2)
\end{aligned}$$

Proof.

$$\begin{aligned}
& \max(\text{zipwith}_4 f_s |s_1| |s_2| |r_1| |l_2|) \\
= & \quad \{ \text{def. of } f_s, \text{zipwith} \} \\
& \quad s_1 \uparrow \max(\text{gemm}(\_, +) r_1 l_2) \uparrow s_2 \\
= & \quad \{ \text{def. of } f'_s, \max, \text{associativity of } \uparrow \} \\
& \quad \max |s_1| \uparrow \max |s_2| \uparrow \max(\text{zipwith } f'_s |r_1| |l_2|)
\end{aligned}$$

$$\begin{aligned}
& \max(\text{zipwith}_4 f_s (s_1^1 \phi s_1^2) (s_2^1 \phi s_2^2) (r_1^1 \phi r_1^2) (l_2^1 \phi l_2^2)) \\
= & \quad \{ \text{def. of } \max, \text{zipwith} \} \\
& \max(\text{zipwith}_4 f_s s_1^1 s_2^1 r_1^1 l_2^1) \uparrow \max(\text{zipwith}_4 f_s s_1^2 s_2^2 r_1^2 l_2^2) \\
= & \quad \{ \text{hypo. of induction} \} \\
& \max s_1^1 \uparrow \max s_2^1 \uparrow \max(\text{zipwith } f'_s r_1^1 l_2^1) \uparrow \max s_1^2 \uparrow \max s_2^2 \uparrow \max(\text{zipwith } f'_s r_1^2 l_2^2) \\
= & \quad \{ \text{def. of } f'_s, \max, \text{associativity of } \uparrow \} \\
& \max(s_1^1 \phi s_1^2) \uparrow \max(s_2^1 \phi s_2^2) \uparrow \max(\text{zipwith } f'_s (r_1^1 \phi r_1^2) (l_2^1 \phi l_2^2))
\end{aligned}$$

The incuntion case for  $\oplus$  is proved similarly.

Then, we prove the following equation by the induction on the structure of abide trees.

$$\max(\text{zipwith } f'_s r_1 l_2) = \max(\text{zipwith}(+) (\text{map reduce}(\uparrow, \_) r_1) (\text{map reduce}(\_, \uparrow) l_2))$$

Proof.

$$\begin{aligned} & \max(\text{zipwith } f'_s |r_1| |l_2|) \\ = & \quad \{ \text{def. of } \max, \text{zipwith}, f'_s \} \\ & \max | \max(\text{gemm}(\_, +) r_1 l_2) | \\ = & \quad \{ \text{below} \} \\ & \max(| \text{reduce}(\uparrow, \_) r_1 + \text{reduce}(\uparrow, \_) l_2 |) \\ = & \quad \{ \text{def. of zipwith, map} \} \\ & \max(\text{zipwith}(+) (\text{map reduce}(\uparrow, \_) |r_1|) (\text{map reduce}(\_, \uparrow) |l_2|)) \end{aligned}$$

$$\begin{aligned} & \max(\text{zipwith } f'_s (r_1^1 \oplus r_1^2) (l_2^1 \oplus l_2^2)) \\ = & \quad \{ \text{def. of } \max, \text{zipwith} \} \\ & \max(\text{zipwith } f'_s r_1^1 l_2^1 \uparrow \max(\text{zipwith } f'_s r_1^2 l_2^2)) \\ = & \quad \{ \text{hypo. of induction} \} \\ & \max(\text{zipwith}(+) (\text{map reduce}(\uparrow, \_) r_1^1) (\text{map reduce}(\_, \uparrow) l_2^1)) \\ & \quad \uparrow \max(\text{zipwith}(+) (\text{map reduce}(\uparrow, \_) r_1^2) (\text{map reduce}(\_, \uparrow) l_2^2)) \\ = & \quad \{ \text{def. of } \max, \text{zipwith}, \text{map} \} \\ & \max(\text{zipwith}(+) (\text{map reduce}(\uparrow, \_) (r_1^1 \oplus r_1^2)) (\text{map reduce}(\_, \uparrow) (l_2^1 \oplus l_2^2))) \end{aligned}$$

To complete the proof of the base case, we prove the next equation by the induction on the structure of abide trees.

$$\begin{aligned} \max(\text{gemm}(\_, +) r_1 l_2) &= \text{reduce}(\uparrow, \_) r_1 + \text{reduce}(\uparrow, \_) l_2 \\ &\Leftarrow \text{width } r_1 = 1, \text{height } l_2 = 1 \end{aligned}$$

Proof.

$$\begin{aligned} & \max(\text{gemm}(\_, +) |r_1| |l_2|) \\ = & \quad \{ \text{def. of } \text{gemm}, \max \} \\ & r_1 + l_2 \\ = & \quad \{ \text{def. of reduce} \} \\ & \text{reduce}(\uparrow, \_) |r_1| + \text{reduce}(\uparrow, \_) |l_2| \end{aligned}$$

$$\begin{aligned}
& \text{max } (\text{gemm}(\_, +) (r_1^1 \ominus r_1^2) (l_2^1 \oplus l_2^2)) \\
= & \quad \{ \text{def. of } \text{gemm}, \text{max} \} \\
& \text{max } (\text{gemm}(\_, +) r_1^1 l_2^1) \uparrow \text{max } (\text{gemm}(\_, +) r_1^1 l_2^2) \\
& \quad \uparrow \text{max } (\text{gemm}(\_, +) r_1^2 l_2^1) \uparrow \text{max } (\text{gemm}(\_, +) r_1^2 l_2^2) \\
= & \quad \{ \text{hypo. of induction} \} \\
& (\text{reduce}(\uparrow, \_) r_1^1 + \text{reduce}(\uparrow, \_) l_2^1) \uparrow (\text{reduce}(\uparrow, \_) r_1^1 + \text{reduce}(\uparrow, \_) l_2^2) \\
& \quad \uparrow (\text{reduce}(\uparrow, \_) r_1^2 + \text{reduce}(\uparrow, \_) l_2^1) \uparrow (\text{reduce}(\uparrow, \_) r_1^2 + \text{reduce}(\uparrow, \_) l_2^2) \\
= & \quad \{ \text{associativity and distributivity} \} \\
& (\text{reduce}(\uparrow, \_) r_1^1 \uparrow \text{reduce}(\uparrow, \_) r_1^2) + (\text{reduce}(\uparrow, \_) l_2^1 \uparrow \text{reduce}(\uparrow, \_) l_2^2) \\
= & \quad \{ \text{def. of reduce} \} \\
& \text{reduce}(\uparrow, \_) (r_1^1 \ominus r_1^2) + \text{reduce}(\uparrow, \_) (l_2^1 \oplus l_2^2)
\end{aligned}$$

### B.13 Rule XIII

$$\begin{aligned}
& \text{reduce}(\oplus, \otimes) (\text{map } f \ x) \\
= & \ f (\text{reduce}(\oplus, \otimes) \ x) \Leftarrow f \ a \ \otimes \ f \ b = f \ (a \ \otimes \ b), f \ a \ \oplus \ f \ b = f \ (a \ \oplus \ b)
\end{aligned}$$

Proof. The induction on the structure of abide trees.

$$\begin{aligned}
& \text{reduce}(\oplus, \otimes) (\text{map } f \ |x|) \\
= & \quad \{ \text{def. of reduce, map} \} \\
& \ f \ x \\
= & \quad \{ \text{def. of reduce} \} \\
& \ f \ (\text{reduce}(\oplus, \otimes) \ |x|)
\end{aligned}$$

$$\begin{aligned}
& \text{reduce}(\oplus, \otimes) (\text{map } f \ (x \ \ominus \ y)) \\
= & \quad \{ \text{def. of reduce, map} \} \\
& \ \text{reduce}(\oplus, \otimes) (\text{map } f \ x) \ \oplus \ \text{reduce}(\oplus, \otimes) (\text{map } f \ y) \\
= & \quad \{ \text{hypo. of induction} \} \\
& \ f \ (\text{reduce}(\oplus, \otimes) \ x) \ \oplus \ f \ (\text{reduce}(\oplus, \otimes) \ y) \\
= & \quad \{ \text{hypo.} \} \\
& \ f \ ((\text{reduce}(\oplus, \otimes) \ x) \ \oplus \ (\text{reduce}(\oplus, \otimes) \ y)) \\
= & \quad \{ \text{def. of reduce} \} \\
& \ f \ (\text{reduce}(\oplus, \otimes) \ (x \ \oplus \ y))
\end{aligned}$$

The incuntion case for  $\ominus$  is proved similarly.

For instance,  $\oplus = \_$  (don't care),  $\otimes = \text{zipwith}(\uparrow)$  and  $f = \text{zipwith}(+) \ c_1$  satisfy the condition  $f \ a \ \otimes \ f \ b = f \ (a \ \otimes \ b)$ .

## B.14 Rule XIV

$$\begin{aligned}
& \text{reduce}(\oplus, \otimes) (\text{zipwith}_4 f x y z w) \\
&= f' (\text{reduce}(\oplus_1, \otimes_1) x) (\text{reduce}(\oplus_2, \otimes_2) y) (\text{reduce}(\oplus_3, \otimes_3) z) (\text{reduce}(\oplus_4, \otimes_4) w) \\
&\Leftarrow f a b c d = f' a b c d, \\
&\quad f' a b c d \oplus f' x y z w = f' (a \oplus_1 x) (b \oplus_2 y) (c \oplus_3 z) (d \oplus_4 w) \\
&\quad f' a b c d \otimes f' x y z w = f' (a \otimes_1 x) (b \otimes_2 y) (c \otimes_3 z) (d \otimes_4 w)
\end{aligned}$$

Proof. The induction on the structure of abide trees.

$$\begin{aligned}
& \text{reduce}(\oplus, \otimes) (\text{zipwith}_4 f |x| |y| |z| |w|) \\
&= \{ \text{def. of reduce, zipwith} \} \\
&\quad f x y z w \\
&= \{ \text{hypo.} \} \\
&\quad f' x y z w \\
&= \{ \text{def. of reduce} \} \\
&\quad f' (\text{reduce}(\oplus_1, \otimes_1) |x|) (\text{reduce}(\oplus_2, \otimes_2) |y|) (\text{reduce}(\oplus_3, \otimes_3) |z|) (\text{reduce}(\oplus_4, \otimes_4) |w|)
\end{aligned}$$

$$\begin{aligned}
& \text{reduce}(\oplus, \otimes) (\text{zipwith}_4 f (x_1 \oplus x_2) (y_1 \oplus y_2) (z_1 \oplus z_2) (w_1 \oplus w_2)) \\
&= \{ \text{def. of reduce, zipwith} \} \\
&\quad \text{reduce}(\oplus, \otimes) (\text{zipwith}_4 f x_1 y_1 z_1 w_1) \oplus \text{reduce}(\oplus, \otimes) (\text{zipwith}_4 f x_2 y_2 z_2 w_2) \\
&= \{ \text{hypo. of induction} \} \\
&\quad f' (\text{reduce}(\oplus_1, \otimes_1) x_1) (\text{reduce}(\oplus_2, \otimes_2) y_1) (\text{reduce}(\oplus_3, \otimes_3) z_1) (\text{reduce}(\oplus_4, \otimes_4) w_1) \\
&\quad \oplus f' (\text{reduce}(\oplus_1, \otimes_1) x_2) (\text{reduce}(\oplus_2, \otimes_2) y_2) (\text{reduce}(\oplus_3, \otimes_3) z_2) (\text{reduce}(\oplus_4, \otimes_4) w_2) \\
&= \{ \text{hypo.} \} \\
&\quad f' (\text{reduce}(\oplus_1, \otimes_1) x_1 \oplus_1 \text{reduce}(\oplus_1, \otimes_1) x_2) (\text{reduce}(\oplus_2, \otimes_2) y_1 \oplus_2 \text{reduce}(\oplus_2, \otimes_2) y_2) \\
&\quad (\text{reduce}(\oplus_3, \otimes_3) z_1 \oplus_3 \text{reduce}(\oplus_3, \otimes_3) z_2) (\text{reduce}(\oplus_4, \otimes_4) w_1 \oplus_4 \text{reduce}(\oplus_4, \otimes_4) w_2) \\
&= \{ \text{def. of reduce} \} \\
&\quad f' (\text{reduce}(\oplus_1, \otimes_1) (x_1 \oplus x_2)) (\text{reduce}(\oplus_2, \otimes_2) (y_1 \oplus y_2)) \\
&\quad (\text{reduce}(\oplus_3, \otimes_3) (z_1 \oplus z_2)) (\text{reduce}(\oplus_4, \otimes_4) (w_1 \oplus w_2))
\end{aligned}$$

The incuntion case for  $\phi$  is proved similarly.

For instance,  $f' a b c d = (a \phi \text{gemm}(\uparrow, +) c d) \oplus (NIL \phi b)$ ,  $\otimes_1 = \text{zipwith}(\uparrow)$ ,  $\otimes_2 = \text{zipwith}(\uparrow)$ ,  $\otimes_3 = \phi$  and  $\otimes_4 = \oplus$  satisfy the condition for  $f a b c d = (a \phi \text{gemm}(\_, +) c d) \oplus (NIL \phi b)$ ,  $\otimes = \text{zipwith}(\uparrow)$  and  $\oplus = \_$ .

## B.15 Rule XV

$$\begin{aligned}
& \text{map} (\text{reduce}(\oplus, \_)) (\text{gemm}(\_, \text{zipwith}(\otimes)) x y) \\
&= \text{gemm}(\oplus, \otimes) (\text{tr} (\text{reduce}(\phi, \_)) x) (\text{reduce}(\_, \phi) y) \\
&\Leftarrow \text{width of } x \text{ and its elements} = 1, \text{width of } y\text{'s elements} = 1, \text{height } y = 1
\end{aligned}$$

Proof. The induction on the structure of abide trees.

$$\begin{aligned}
& \text{map } (\text{reduce}(\oplus, \_)) (\text{gemm}(\_, \text{zipwith}(\otimes)) |x| |y|) \\
= & \quad \{ \text{def. of map, gemm} \} \\
& | \text{reduce}(\oplus, \_) x y | \\
= & \quad \{ \text{below} \} \\
& \text{gemm} (\oplus, \otimes) (\text{tr } x) y \\
= & \quad \{ \text{def. of reduce} \} \\
& \text{gemm} (\oplus, \otimes) (\text{tr } (\text{reduce } (\phi, \_) |x|)) (\text{reduce } (\_, \phi) |y|)
\end{aligned}$$

$$\begin{aligned}
& \text{map } (\text{reduce}(\oplus, \_)) (\text{gemm}(\_, \text{zipwith}(\otimes)) (x_1 \oplus x_2) (y_1 \phi y_2)) \\
= & \quad \{ \text{def. of map, gemm} \} \\
& (\text{map } (\text{reduce}(\oplus, \_)) (\text{gemm}(\_, \text{zipwith}(\otimes)) x_1 y_1) \phi \text{map } (\text{reduce}(\oplus, \_)) (\text{gemm}(\_, \text{zipwith}(\otimes)) x_1 y_2)) \\
& \oplus (\text{map } (\text{reduce}(\oplus, \_)) (\text{gemm}(\_, \text{zipwith}(\otimes)) x_2 y_1) \phi \text{map } (\text{reduce}(\oplus, \_)) (\text{gemm}(\_, \text{zipwith}(\otimes)) x_2 y_2)) \\
= & \quad \{ \text{hypo. of induction} \} \\
& (\text{gemm} (\oplus, \otimes) (\text{tr } (\text{reduce } (\phi, \_) x_1)) (\text{reduce } (\_, \phi) y_1)) \\
& \phi \text{gemm} (\oplus, \otimes) (\text{tr } (\text{reduce } (\phi, \_) x_1)) (\text{reduce } (\_, \phi) y_2)) \\
& \oplus (\text{gemm} (\oplus, \otimes) (\text{tr } (\text{reduce } (\phi, \_) x_2)) (\text{reduce } (\_, \phi) y_1)) \\
& \phi \text{gemm} (\oplus, \otimes) (\text{tr } (\text{reduce } (\phi, \_) x_2)) (\text{reduce } (\_, \phi) y_2)) \\
= & \quad \{ \text{def. of gemm} \} \\
& \text{gemm} (\oplus, \otimes) (\text{tr } (\text{reduce } (\phi, \_) x_1) \phi \text{tr } (\text{reduce } (\phi, \_) x_2)) (\text{reduce } (\_, \phi) y_1 \phi \text{reduce } (\_, \phi) y_2)) \\
= & \quad \{ \text{def. of tr, reduce} \} \\
& \text{gemm} (\oplus, \otimes) (\text{tr } (\text{reduce } (\phi, \_) (x_1 \oplus x_2))) (\text{reduce } (\_, \phi) (y_1 \phi y_2))
\end{aligned}$$

To complete the proof, we prove the following equation by the induction on the structure of abide trees.

$$\begin{aligned}
& | \text{reduce}(\oplus, \_) (\text{zipwith}(\otimes) x y) | = \text{gemm}(\oplus, \otimes) (\text{tr } x) y \\
& \Leftarrow \text{width } x = 1, \text{width } y = 1
\end{aligned}$$

Proof.

$$\begin{aligned}
& | \text{reduce}(\oplus, \_) (\text{zipwith}(\otimes) |x| |y|) | \\
= & \quad \{ \text{def. of zipwith, reduce} \} \\
& | x \otimes y | \\
= & \quad \{ \text{def. of gemm, tr} \} \\
& \text{gemm}(\oplus, \otimes) (\text{tr } |x|) |y|
\end{aligned}$$



$$\begin{aligned}
& | \text{reduce}(\oplus, \_) (\text{zipwith}(\otimes) (x_1 \ominus x_2) (y_1 \ominus y_2)) | \\
= & \{ \text{def. of zipwith, reduce} \} \\
& | \text{reduce}(\oplus, \_) (\text{zipwith}(\otimes) x_1 y_1) \oplus \text{reduce}(\oplus, \_) (\text{zipwith}(\otimes) x_2 y_2) | \\
= & \{ \text{def. of zipwith} \} \\
& \text{zipwith}(\oplus) | \text{reduce}(\oplus, \_) (\text{zipwith}(\otimes) x_1 y_1) | | \text{reduce}(\oplus, \_) (\text{zipwith}(\otimes) x_2 y_2) | \\
= & \{ \text{hypo. of induction} \} \\
& \text{zipwith}(\oplus) (\text{gemm}(\oplus, \otimes) (\text{tr } x_1) y_1) (\text{gemm}(\oplus, \otimes) (\text{tr } x_2) y_2) \\
= & \{ \text{def. of gemm, tr} \} \\
& \text{gemm}(\oplus, \otimes) (\text{tr } (x_1 \ominus x_2)) (y_1 \ominus y_2)
\end{aligned}$$

### B.16 Rule XVI

$$\begin{aligned}
& \text{map} (\text{reduce}(\_, \oplus)) (\text{gemm}(\_, \text{zipwith}(\otimes)) x y) \\
= & \text{gemm}(\oplus, \otimes) (\text{reduce}(\ominus, \_) x) (\text{tr}(\text{reduce}(\_, \ominus) y)) \\
\Leftarrow & \text{width } x = 1, \text{height of } x\text{'s elements} = 1, \text{height of } y \text{ and its elements} = 1
\end{aligned}$$

Proof. Silimar to Rule XV.

### B.17 Rule XVII

$$\begin{aligned}
& \text{map}(\text{reduce}(\uparrow, \_)) (\text{zipwith}_3 f_r r_1 r_2 r_{o2}) = \text{zipwith}_3 f'_r (\text{reduce}(\uparrow) r_1) r_{o2} (\text{reduce}(\uparrow, \_) r_2) \\
\text{where } & f_r r_1 r_2 r_{o2} = \text{map} (+r_{o2}) r_1 \phi r_2 \\
& f'_r r_1 r_{o2} r_2 = (r_1 + r_{o2}) \uparrow r_2
\end{aligned}$$

Proof. Rule VII and follwing calculation.

$$\begin{aligned}
& \text{reduce}(\uparrow, \_) (f_r r_1 r_2 r_{o2}) \\
= & \{ \text{def. of } f_r \} \\
& \text{reduce}(\uparrow, \_) ((\text{map} (+r_{o2}) r_1) \phi r_2) \\
= & \{ \text{def. of reduce} \} \\
& \text{reduce}(\uparrow, \_) (\text{map} (+r_{o2}) r_1) \uparrow r_2 \\
= & \{ + \text{ distributes over } \uparrow \} \\
& ((\text{reduce}(\uparrow, \_) r_1) + r_{o2}) \uparrow r_2
\end{aligned}$$

### B.18 Rule XVIII

$$\begin{aligned}
& \text{reduce}(\_, \phi) (\text{map} (\text{zipwith}(+) (\text{right}' x)) y) \\
= & \text{map}_c (\text{zipwith}(+) (\text{right} (\text{reduce}(\_, \phi) x))) (\text{reduce}(\_, \phi) y) \\
\Leftarrow & \text{height } x = 1, \text{width of } x\text{'s elements} = 1
\end{aligned}$$

Proof. First, we prove the next equation by the induction on the structure of abide trees.

$$\begin{aligned}
& \text{reduce}(\_, \phi) (\text{map } f x) = \text{map}_c f (\text{reduce}(\_, \phi) x) \\
\Leftarrow & \text{height } x = 1, \text{width of } x\text{'s elements} = 1
\end{aligned}$$

Proof.

$$\begin{aligned}
& \text{reduce}(\_, \phi) (\text{map } f \ |x|) \\
= & \quad \{ \text{def. of reduce, map} \} \\
& f \ x \\
= & \quad \{ \text{def. of map}_c, \text{height } x = 1 \} \\
& \text{map}_c \ f \ x \\
= & \quad \{ \text{def. of reduce} \} \\
& \text{map}_c \ f \ (\text{reduce}(\_, \phi) \ |x|)
\end{aligned}$$

$$\begin{aligned}
& \text{reduce}(\_, \phi) (\text{map } f \ (x_1 \ \phi \ x_2)) \\
= & \quad \{ \text{def. of reduce, map} \} \\
& \text{map } f \ x_1 \ \phi \ \text{map } f \ x_2 \\
= & \quad \{ \text{hypo. of induction} \} \\
& \text{map}_c \ f \ (\text{reduce}(\_, \phi) \ x_1) \ \phi \ \text{map}_c \ f \ (\text{reduce}(\_, \phi) \ x_2) \\
= & \quad \{ \text{def. of map}_c \} \\
& \text{map}_c \ f \ (\text{reduce}(\_, \phi) \ (x_1 \ \phi \ x_2))
\end{aligned}$$

To complete the proof, we prove the next equation by the induction on the structure of abide trees.

$$\begin{aligned}
\text{right}' \ x &= \text{right} (\text{reduce}(\_, \phi) \ x) \\
&\Leftarrow \text{height } x = 1, \text{width of } x\text{'s elements} = 1
\end{aligned}$$

Proof.

$$\begin{aligned}
& \text{right}' \ |x| \\
= & \quad \{ \text{def. of right}' \} \\
& x \\
= & \quad \{ \text{def. of right, width } x = 1 \} \\
& \text{right } x \\
= & \quad \{ \text{def. of reduce} \} \\
& \text{right} (\text{reduce}(\_, \phi) \ |x|)
\end{aligned}$$

$$\begin{aligned}
& \text{right}' \ (x_1 \ \phi \ x_2) \\
= & \quad \{ \text{def. of right}' \} \\
& \text{right}' \ x_2 \\
= & \quad \{ \text{hypo. of induction} \} \\
& \text{right} (\text{reduce}(\_, \phi) \ x_2) \\
= & \quad \{ \text{def. of right} \} \\
& \text{right} (\text{reduce}(\_, \phi) \ x_1 \ \phi \ \text{reduce}(\_, \phi) \ x_2) \\
= & \quad \{ \text{def. of reduce} \} \\
& \text{right} (\text{reduce}(\_, \phi) \ (x_1 \ \phi \ x_2))
\end{aligned}$$

**B.19 Rule XIX**

$$\begin{aligned}
& \text{reduce}(\phi, \_) (\text{map} (\text{zipwith}(+) (\text{top}' x)) y) \\
&= \text{map}_c (\text{zipwith}(+) (\text{top} (\text{reduce}(\phi, \_) x))) (\text{reduce}(\phi, \_) y) \\
&\Leftarrow \text{width } x = 1, \text{width of } x\text{'s elements} = 1
\end{aligned}$$

Proof. Similar to Rule XVIII.

**B.20 Rule XX**

$$\begin{aligned}
& \text{reduce}(\_, \phi) (\text{zipwith } f x y) \\
&= \text{map}_r (\text{zipwith}(+) (\text{top} (\text{reduce}(\_, \phi) y))) (\text{reduce}(\phi, \_) x) \oplus (\text{reduce}(\phi, \_) y) \\
&\Leftarrow \text{height } x = 1, \text{height } y = 1, \text{width of } x \text{ and } y\text{'s elements} = 1 \\
& f x y = \text{map} (+(\text{top}' y)) x \oplus y
\end{aligned}$$

Proof. Rule XIV with  $f' a b = \text{map}_r (\text{zipwith}(+) (\text{top } b)) a \oplus b$  and  $\otimes = \phi, \otimes_1 = \phi, \otimes_2 = \phi$ .

**B.21 Rule XXI**

$$\begin{aligned}
& \text{reduce}(\_, \phi) (\text{zipwith } f x y) \\
&= \text{map}_r (\text{zipwith}(+) (\text{top} (\text{reduce}(\_, \phi) y))) (\text{reduce}(\phi, \_) x) \oplus (\text{reduce}(\phi, \_) y) \\
&\Leftarrow \text{width } x = 1, \text{width } y = 1, \text{width of } x \text{ and } y\text{'s elements} = 1 \\
& f x y = \text{map} (+(\text{top}' y)) x \oplus y
\end{aligned}$$

Proof. Rule XIV with  $f' a b = \text{map}_r (\text{zipwith}(+) (\text{top } b)) a \oplus b$  and  $\oplus = \phi, \oplus_1 = \phi, \oplus_2 = \phi$ .